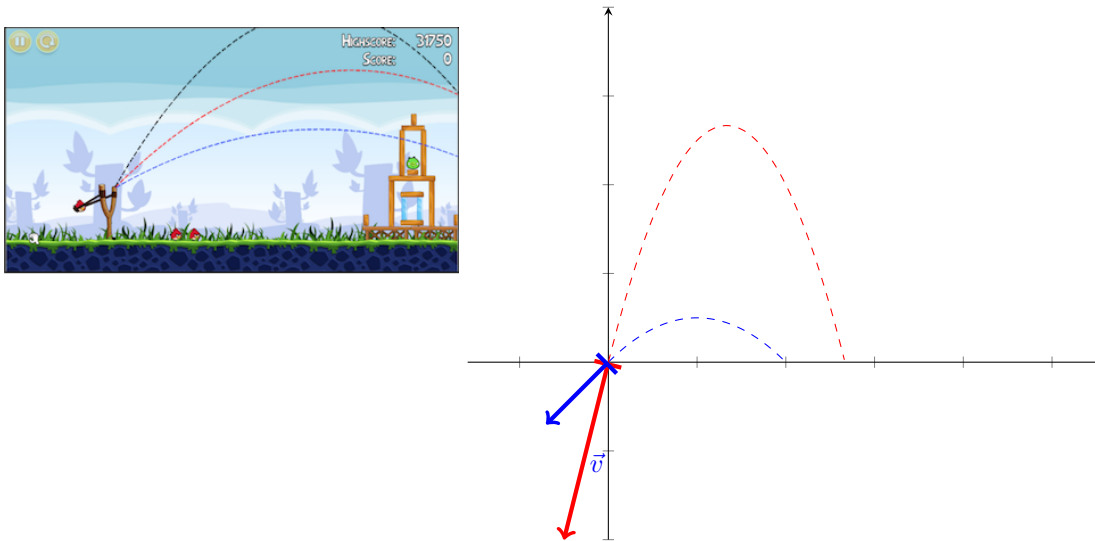


1. You are developing a prototype Angry Birds software to help high school students understand vectors and linear algebra. You would like students to input a vector, $\vec{v} = (v_1, v_2)$, and have the output, $f(\vec{v}) = (a_1, a_2, a_3)$ be the coefficients of a quadratic equation that corresponds to the direction and scale of the vector:

$$y = a_1x^2 + a_2x + a_3.$$



- (a) Suppose that your vector is based at the origin. What does this mean for the value a_3 ?

Solution: $a_3 = 0$.

- (b) Note that \vec{v} points the **opposite direction** of the flight of the bird. It is required that birds land in front of their launch point at $(0,0)$. What constraints does this impose on v_1 and v_2 ? Write them down, or explain why there are none.

Solution: $v_1, v_2 < 0$.

- (c) Write the equation that corresponds to $\text{Span}\{\vec{v}\}$.

Solution:

$$y = \frac{v_2}{v_1}x.$$

- (d) You want the slope of the tangent line to the quadratic and the line from part (c) to agree at 0. Write the corresponding linear equation.

Solution: The quadratic has derivative $y' = 2 * a_1x + a_2$. At $x = 0$ this is equal to a_2 . The slope in part (c) is v_2/v_1 . So we need

$$a_2 = v_2/v_1$$

- (e) Suppose you decide to set $a_1 = v_1 + v_2$. Explain why this is a reasonable choice.

Solution: $v_1 + v_2$ is negative, so the parabola arcs the correct way. Also, as v_1 and v_2 become more negative this will make the arc of the parabola higher.

- (f) Write a matrix corresponding to the system of equations for
- a_1, a_2, a_3
- .

Solution:

$$\begin{bmatrix} 1 & 0 & 0 & v_1 + v_2 \\ 0 & 1 & 0 & v_2/v_1 \\ 0 & 0 & 1 & 0 \end{bmatrix}.$$

- (g) A student asks whether you can now find
- \vec{v}
- so that the bird passes through two specified points
- $(a, b), (c, d)$
- . Write the system of equations that
- \vec{v}
- must satisfy for this to happen.

Solution: We know that $(0, 0)$ is also on the parabola. So we need a parabola that goes through the points $(0, 0), (a, b), (c, d)$. This means that

$$\begin{aligned} a_3 &= 0 \\ a_1 a^2 + a_2 a + a_3 &= b \\ a_1 c^2 + a_2 c + a_3 &= d \end{aligned}$$

- (h) Is it possible if instead three arbitrary points are specified? Why or why not?

Solution: No. A parabola is determined by 3 points, and $(0, 0)$ is already implicitly one of them. So we would have 4 points.

- (i) You input your answer from part (g) into a computer and obtain the system in echelon form:

$$\left(\begin{array}{ccc|c} 1 & 0 & 0 & \frac{b}{a^2} + \frac{\frac{bc^2-d}{a^2}}{a\left(c-\frac{c^2}{a}\right)} \\ 0 & 1 & 0 & -\frac{\frac{bc^2-d}{a^2}}{c-\frac{c^2}{a}} \\ 0 & 0 & 1 & 0 \end{array} \right)$$

What values of (a, b, c) are not acceptable. Explain why. Don't just say because the matrix equations don't make sense.

Solution: $a = 0$ is not acceptable since this would give a redundant point $(0, 0)$ which is not enough information to uniquely determine the parabola. Also, $c = a$ is not acceptable. This corresponds to (a, b) and (c, d) lying on the same vertical line, which is unacceptable because a parabola is a function, so it cannot go through two points on the same vertical line.

- (j) Let

$$g(a, b) = \frac{b}{a^2} + \frac{\frac{bc^2-d}{a^2}}{a\left(c-\frac{c^2}{a}\right)} \quad \text{and} \quad h(a, b) = -\frac{\frac{bc^2-d}{a^2}}{c-\frac{c^2}{a}}.$$

Given $(a, b), (c, d)$ write a **linear** system of equations for v_1 and v_2 in terms of $h(a, b)$ and $g(a, b)$.

Solution: $v_1 + v_2 = g(a, b)$ and $v_2/v_1 = h(a, b)$. So we have a linear system:

$$\begin{aligned} v_1 + v_2 &= g(a, b) \\ -h(a, b)v_1 + v_2 &= 0. \end{aligned}$$

- (k) What is the solution to this equation?

Solution: We can add $h(a, b)$ times the first equation to the second. This gives $(h(a, b)+1)v_2 = h(a, b)g(a, b)$. So

$$v_2 = \frac{h(a, b)g(a, b)}{h(a, b) + 1}.$$

This means that $v_1 = g(a, b) - \frac{h(a, b)g(a, b)}{h(a, b)+1}$.

2. A video game designer is rectifying the dynamics of two different rooms in a video game. She needs to know if $\left\{ \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \right\}$ and $\left\{ \begin{bmatrix} 4 \\ 2 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \right\}$ have the same span.

- (a) Call (x, y, z) a point in the span of a set of vectors. Write down two augmented matrices that correspond to the span of the two sets of vectors above.

Solution:

$$\begin{bmatrix} 1 & 2 & x \\ 2 & 3 & y \\ 2 & 4 & z \end{bmatrix} \qquad \begin{bmatrix} 4 & 1 & x \\ 2 & 3 & y \\ 6 & 2 & z \end{bmatrix}$$

- (b) Say you row reduce these matrices. What must happen for them to have the same span?

Solution: When row reduced they will look like

$$\begin{bmatrix} 1 & 0 & f_1(x, y, z) \\ 0 & 1 & f_2(x, y, z) \\ 0 & 0 & f_3(x, y, z) \end{bmatrix} \qquad \begin{bmatrix} 1 & 0 & g_1(x, y, z) \\ 0 & 1 & g_2(x, y, z) \\ 0 & 0 & g_3(x, y, z) \end{bmatrix},$$

with f_i and g_i linear equations. The span is described by the set of points where $f_3(x, y, z) = 0$, and the span for the second set is where $g_3(x, y, z) = 0$. To be the same we need $f_3(x, y, z) = Cg_3(x, y, z)$ for some constant C .

3. Byeol is a programmer at Google and she is given a piece of code which she is told starts with two vectors $\{\vec{u}, \vec{v}\}$ (that she does not know) and ultimately outputs $\{\vec{u} + \vec{v}, \vec{u} - \vec{v}\}$.

- (a) Is it possible to determine the values of \vec{u} and \vec{v} from the output? Explain.

Solution: Yes. Set $\vec{u} + \vec{v} = \vec{x}$ and $\vec{u} - \vec{v} = \vec{y}$. Adding the two equations we have $2\vec{u} = \vec{x} + \vec{y}$ and thus $\vec{u} = \frac{1}{2}(\vec{x} + \vec{y})$. Similarly, $\vec{v} = \frac{1}{2}(\vec{x} - \vec{y})$.

- (b) Byeol is told that \vec{u} and \vec{v} are linearly independent. She needs to know that the output also is. Show that $\vec{u} + \vec{v}$ and $\vec{u} - \vec{v}$ are also linearly independent

Solution: Because \vec{u} and \vec{v} are linearly independent we know that $\vec{u} \neq c\vec{v}$ for all constants c . However, if $\vec{u} + \vec{v}$ and $\vec{u} - \vec{v}$ were *not* linearly independent, then we could write $\vec{u} + \vec{v} = b(\vec{u} - \vec{v})$ for some constant b . Note that when $b = -1$ we would have

$$\vec{u} + \vec{v} = -\vec{u} + \vec{v},$$

which says that $2\vec{u} = \vec{0}$. This is impossible if \vec{u} and \vec{v} are linearly independent, because any collection of vectors containing $\vec{0}$ is linearly dependent.

Now suppose $b \neq -1$. Rearranging $\vec{u} + \vec{v} = b(\vec{u} - \vec{v})$ we have

$$\vec{u} + b\vec{u} = \vec{v} - b\vec{v}.$$

This is equivalent to $\vec{u} = \frac{1-b}{1+b}\vec{v}$. Since $b \neq -1$, we can set $c = \frac{1-b}{1+b}$, this contradicts the fact that $\vec{u} \neq c\vec{v}$ for all c . So, there *cannot* exist such a b . This is equivalent to linear independence of the vectors in question.