

LAKSHYA BATCH



Magnetism and Matter

**Magnetic field due to bar Magnet,
Torque, work and Questions**

LECTURE - 2



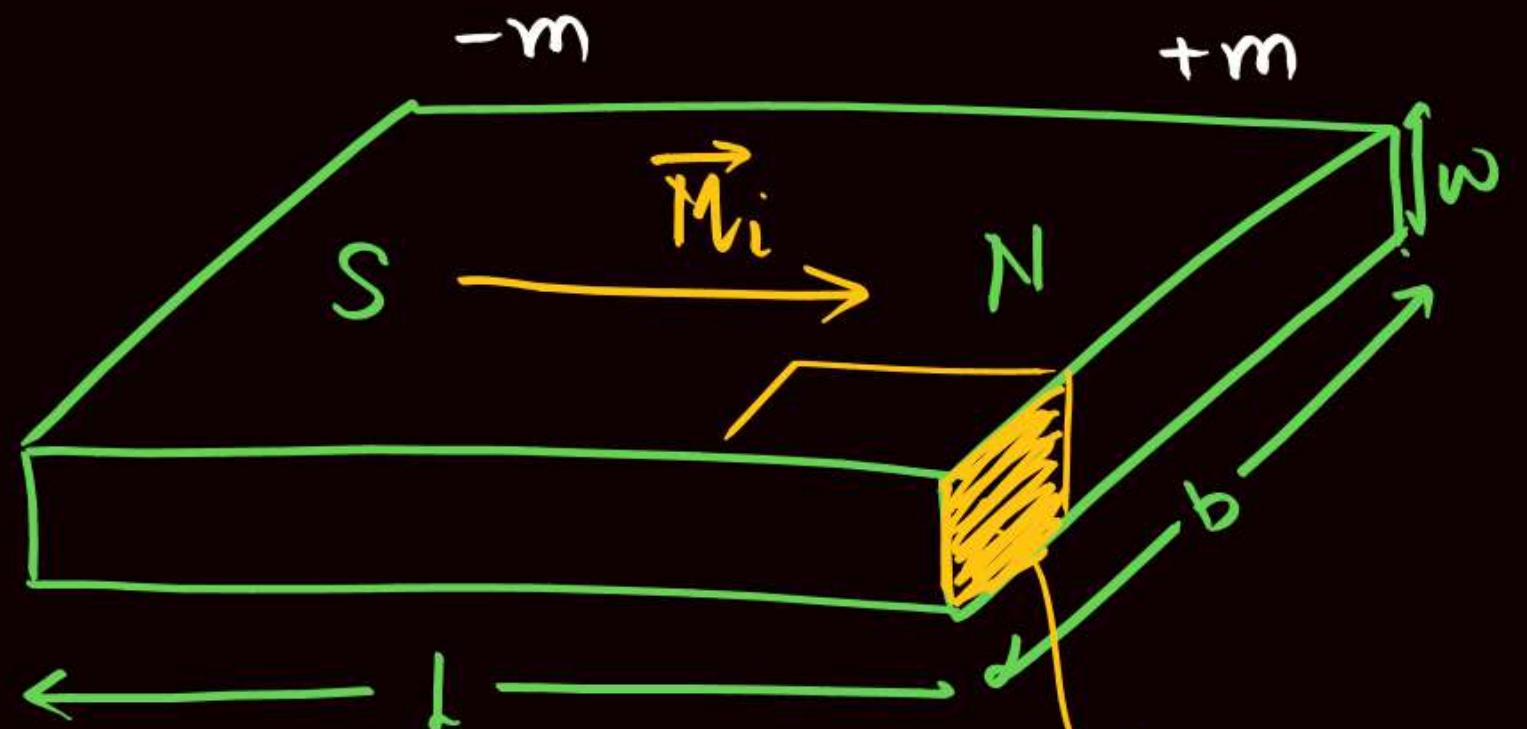
GOALS OF THE DAY

- ❖ Magnetic field at axial and equatorial points Not in CBSE
 - ❖ Torque on dipole (Not in CBSE)
 - ❖ Work done in rotation of dipole (Not in CBSE)
- but in Mains, Not in Advance



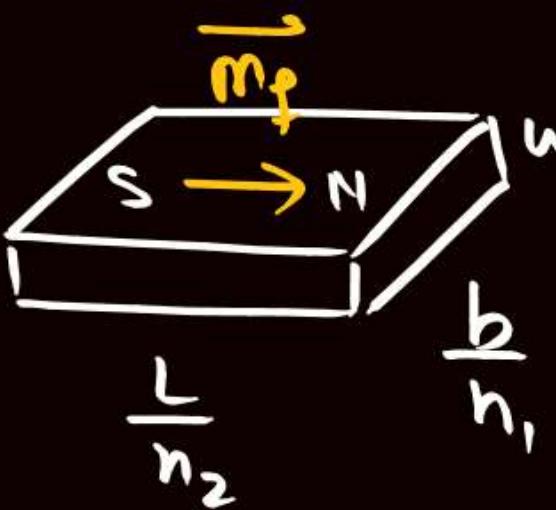
- # The pain you feel today, will be strength you feel tomorrow. Let's Get to work!
- # Successful people will always question whether they're still doing enough, while unsuccessful people are satisfied with what they are doing.
- # We are born weak & die weak. But what you are in between is only upto you. →

$$A_i^o = b\omega$$



$$A_i = \frac{b}{n_1} \omega$$

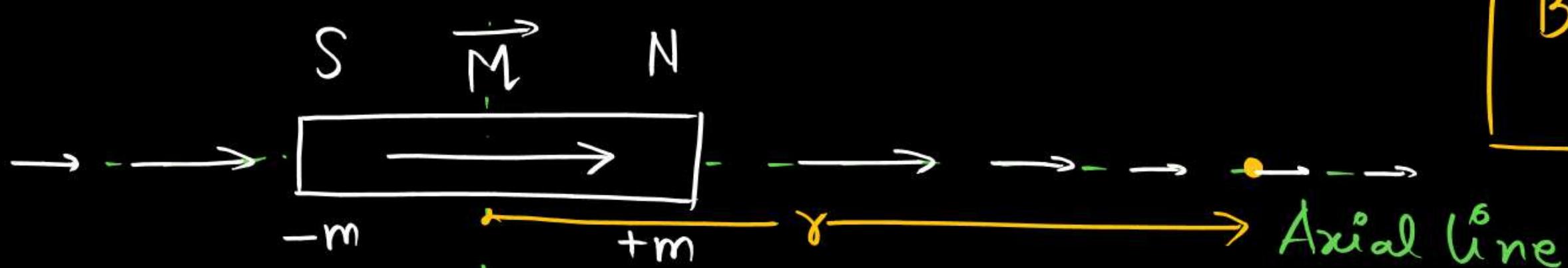
$$A_f = \frac{A_i}{n_1}$$



Pole strength
 $new = \frac{m}{n_1}$

$$\vec{M}_f = \frac{m}{n_1} \frac{L}{n_2} = \frac{mL}{n_1 n_2} = \frac{\vec{M}_i}{n_1 n_2}$$

Magnetic field Due to Bar magnets



$$\boxed{B_{\text{Axial Point}} = \frac{\mu_0 2M}{4\pi r^3}}$$

$$\boxed{B \propto \frac{1}{r^3}}$$

Equatorial line

- ④ direction of MF is in direction of Magnetic dipole Moment.



Magnetic field Due to Bar magnets

Case. Equitorial points.

$$|B_e| = \frac{\mu_0 M}{4\pi r^3}$$



$$B \propto \frac{1}{r^3}$$

direction of MF

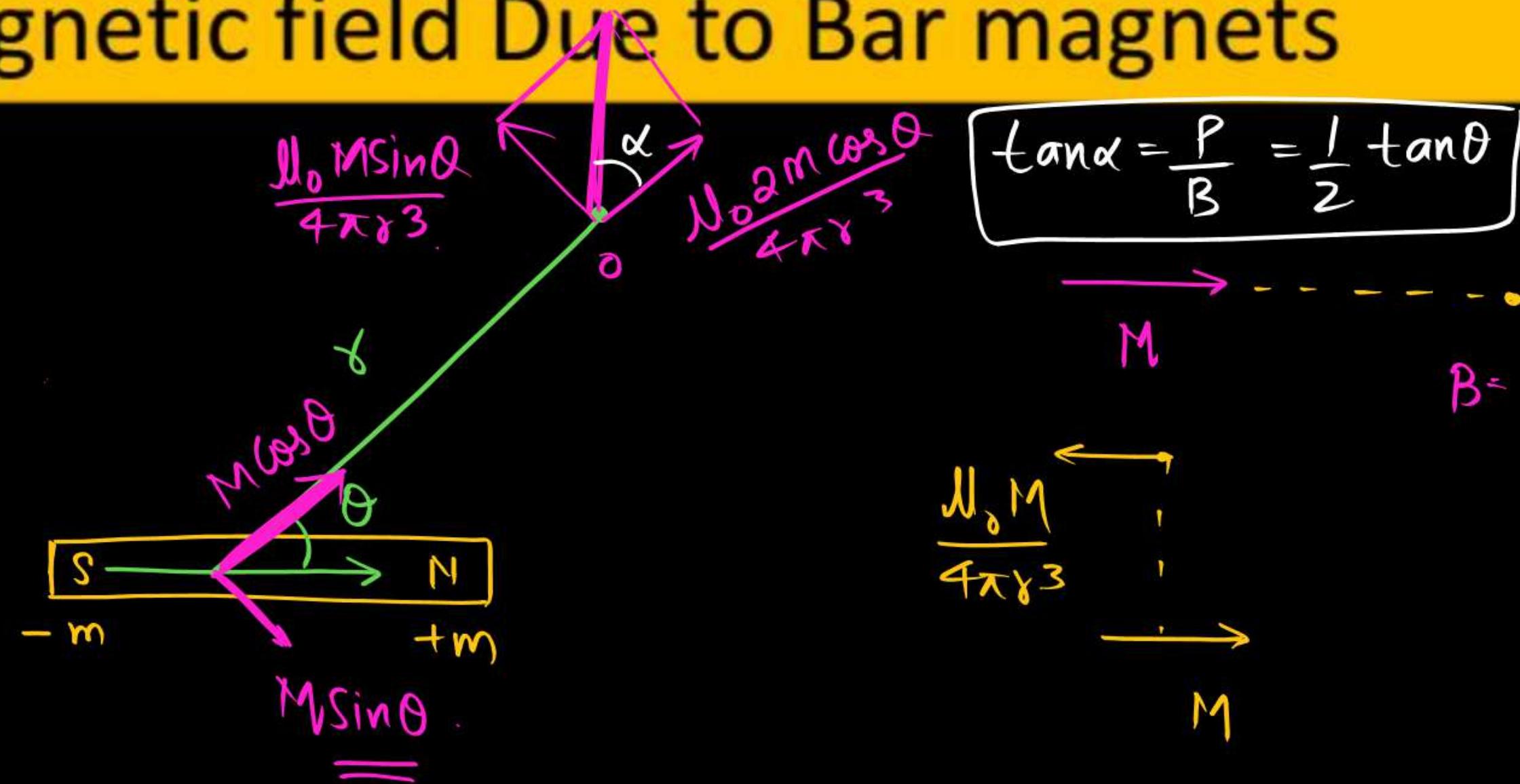
at Equitorial point

is anti parallel to \vec{M} .



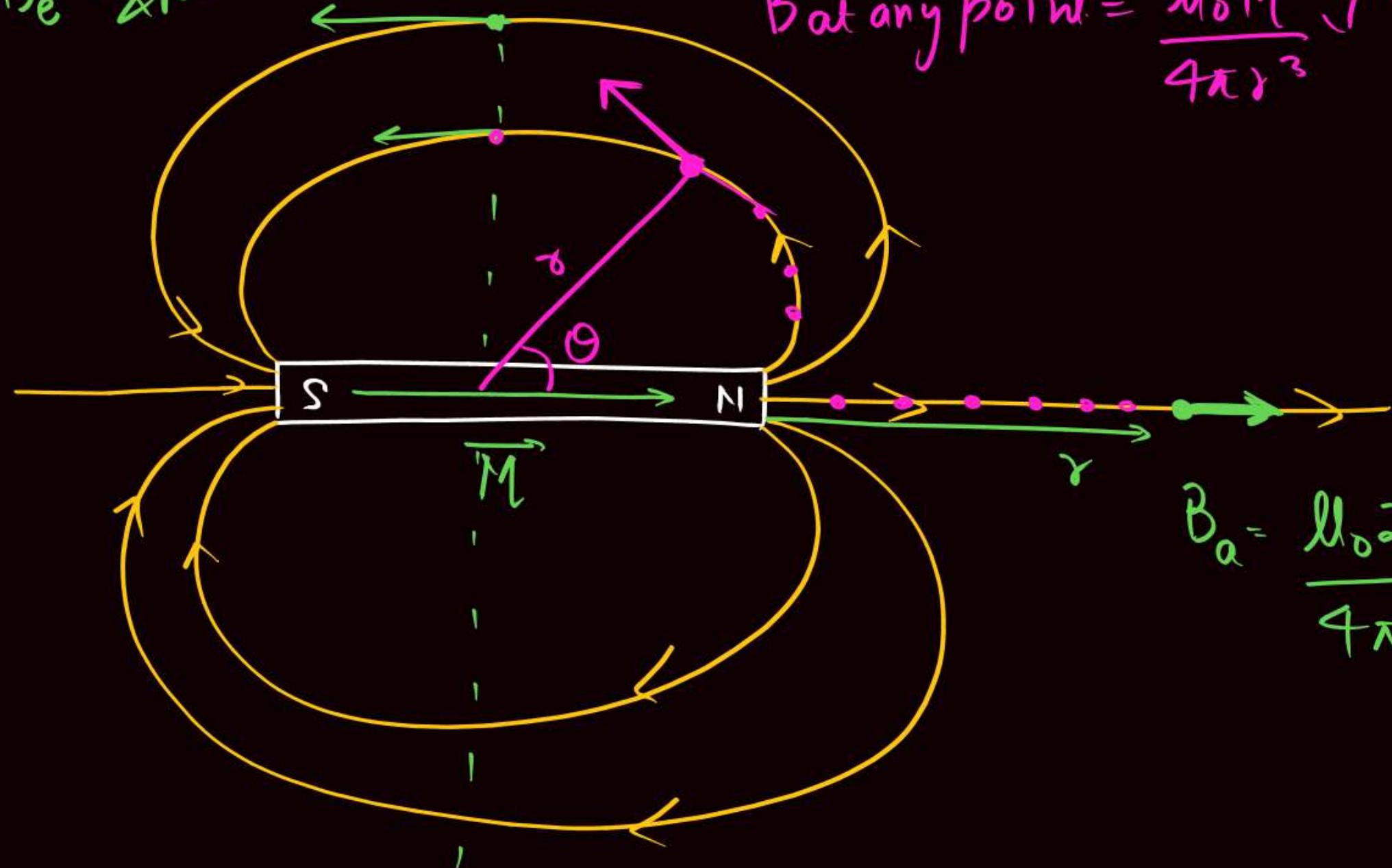
$$B_\theta = \frac{\mu_0 M}{4\pi r^3} \sqrt{3(\cos^2 \theta + 1)}$$

Magnetic field Due to Bar magnets



$$B_e = \frac{\mu_0 M}{4\pi r^3}$$

Equatorial Points



$$\text{At any point} = \frac{\mu_0 M}{4\pi r^3} \sqrt{3 \cos^2 \theta + 1}$$

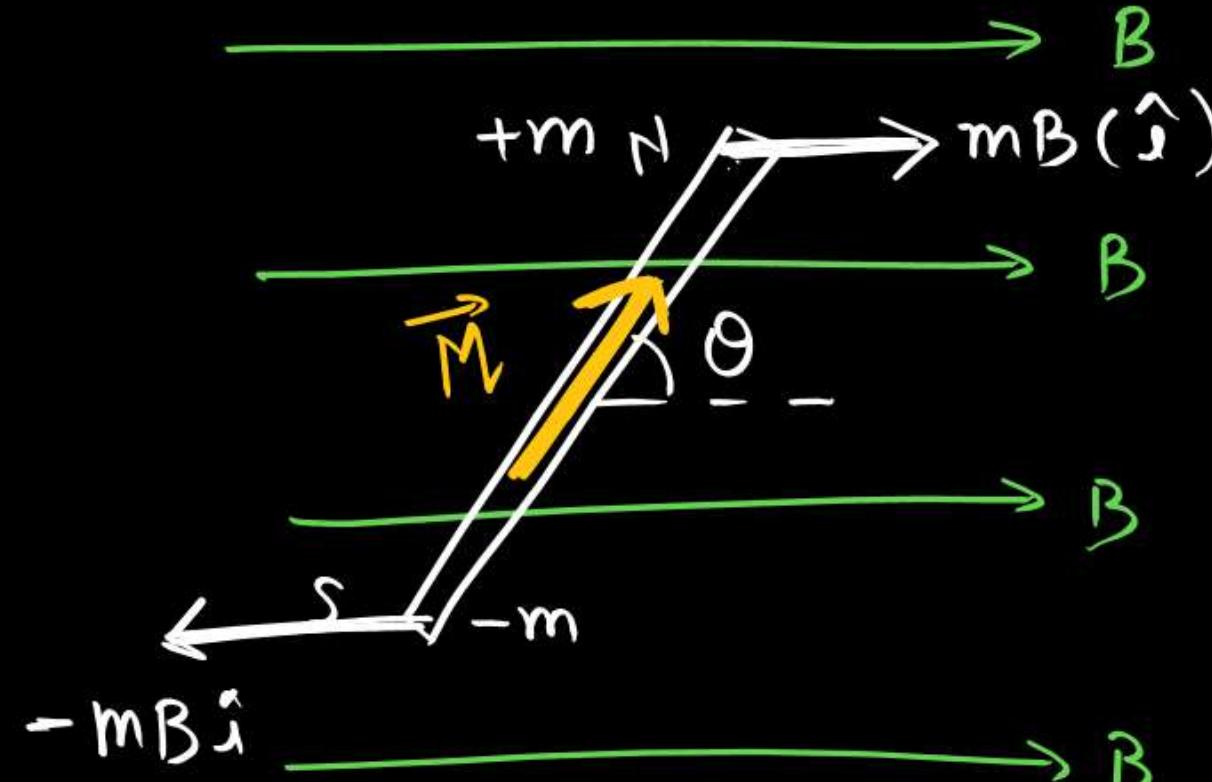
$$\text{If } \theta = 0^\circ \quad B_e = \frac{\mu_0 2M}{4\pi r^3}$$

$$B_e = \frac{\mu_0 M}{4\pi r^3}$$

$$B_a = \frac{\mu_0 2M}{4\pi r^3}$$

$$\boxed{\frac{B_a}{B_e} = 2}$$

Torque on Magnetic dipole



$$\text{Torque} = \vec{M} \times \vec{B}$$

$$|\tau| = MB \sin \theta$$

$$\tau_{\max}$$

$$\theta = 90^\circ$$

$$\tau_{\max} = MB$$

$$\tau_{\min} \theta = 0, 180^\circ$$

$$\tau = 0$$

#

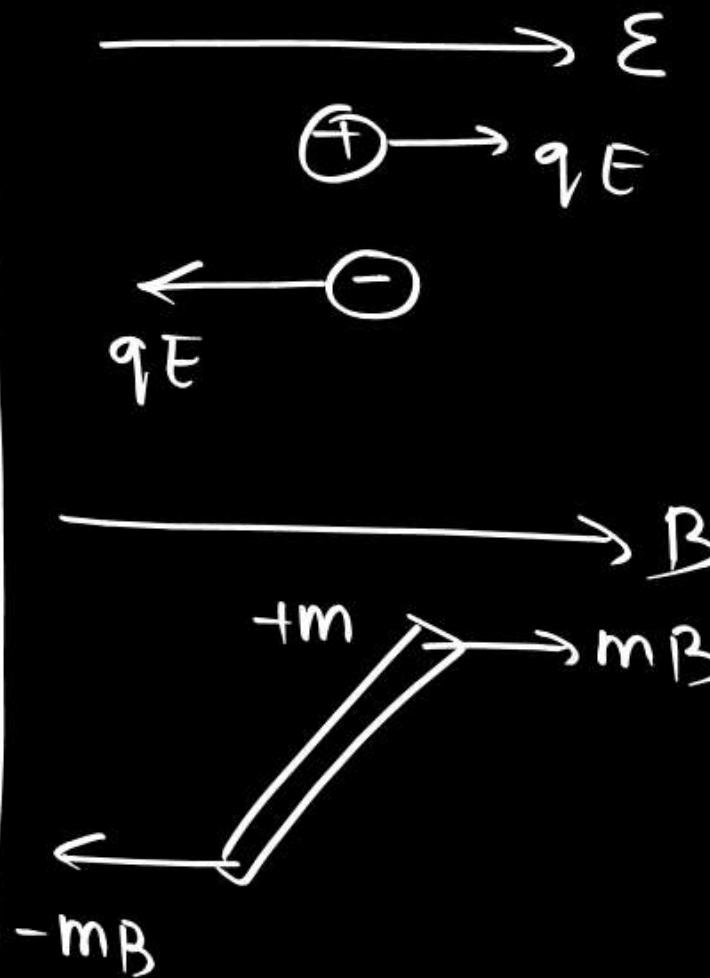
$$f_{\text{net}} = 0$$

in uniform \vec{B} .

Torque may or may not be zero

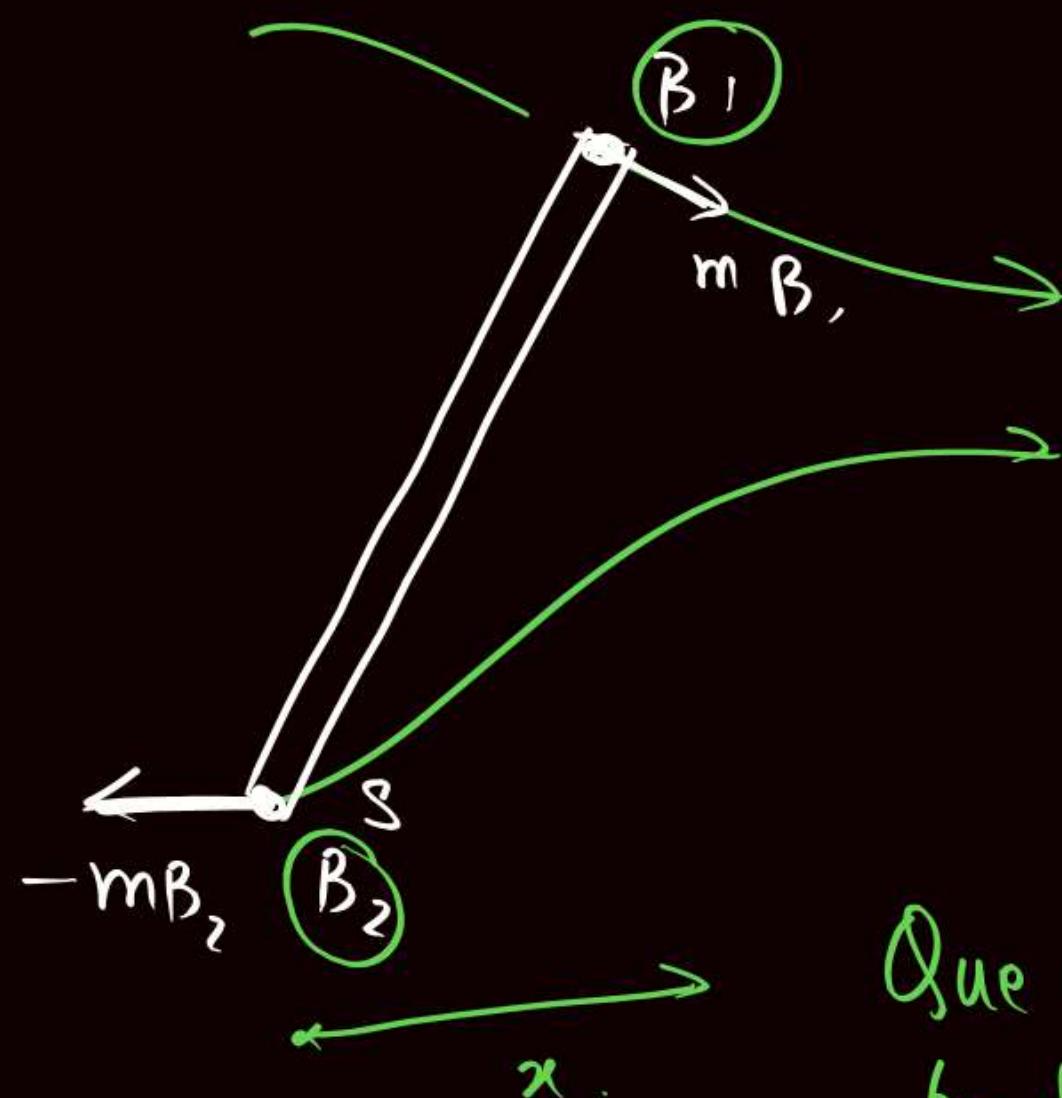


In Electro



Mains

If $\vec{M}\vec{F}$ is Non uniform



Ques will
be done
in Practice.

$F_{Total} =$ will not be zero.

∴ not zero

for Mains ***

force on dipole in non uniform

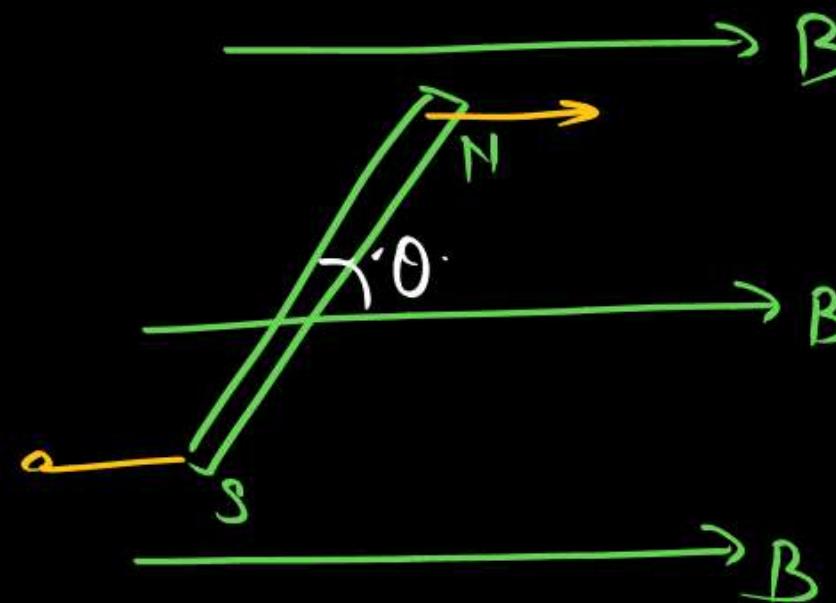
Field

$$F = M \frac{d\vec{B}}{dx}$$

$\frac{d\vec{B}}{dx} \Rightarrow$ Rate of change of
 B w.r.t x .

Work done and Potential energy

When we Rotate a dipole work has to be done.



$$dW = \tau d\theta$$

$$dW = MB \sin \theta d\theta$$

$$W_T = -MB \cos \theta$$

$$W = -\vec{M} \cdot \vec{B}$$

$$PE = -\vec{M} \cdot \vec{B}$$

If it is Rotated from θ_1 to θ_2

$$W = MB [\cos \theta_1 - \cos \theta_2]$$

In Electro

$$\tau = \vec{P} \times \vec{\epsilon}$$

$$PE = W = -\vec{P} \cdot \vec{\epsilon}$$

$$W = PE (\cos \theta_1 - \cos \theta_2)$$

$P \rightarrow M$
$\epsilon \rightarrow B$



Only mains find the force of interaction between two dipoles.

Case 0

Class II

$$\vec{F} = -\frac{\partial U}{\partial r}$$

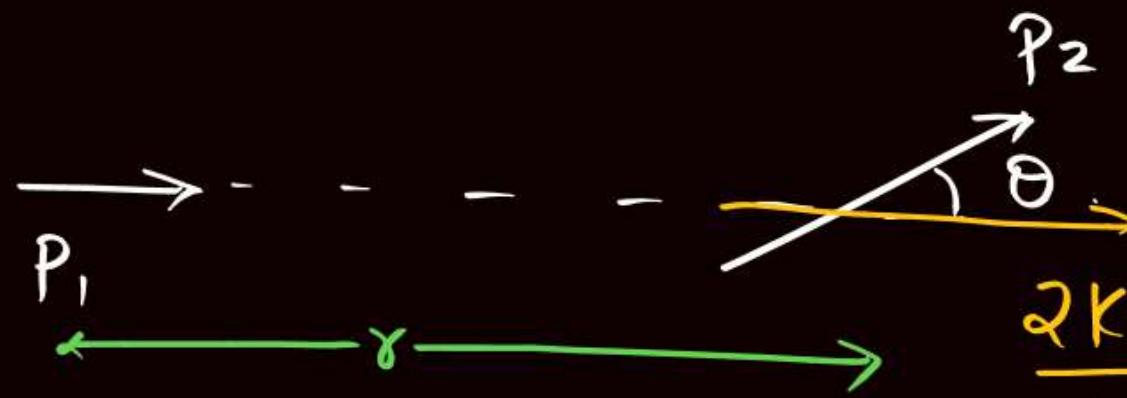
Case I

Attract

$$\vec{P}_1 \rightarrow \vec{P}_2 \rightarrow f = -\frac{6K P_1 P_2}{r^4}$$

$$\vec{P}_1 \rightarrow \vec{P}_2 \leftarrow \vec{P}_2 \quad f = \frac{6K P_1 P_2}{r^4}$$

Repel



$$PE = -\vec{P}_2 \cdot \vec{\epsilon}_1$$

$$U = -\frac{P_2 2K P_1 \cos \theta}{r^3}$$

$$f = -\frac{\partial}{\partial r} \left[-\frac{2K P_1 P_2 \cos \theta}{r^3} \right]$$

$$= +2K P_1 P_2 \cos \theta \frac{\partial}{\partial r} r^{-3}$$

$$= -6K P_1 P_2 \cos \theta \frac{1}{r^4}$$

$$= -\frac{6K P_1 P_2 \cos \theta}{r^4}$$

If we have to find force

Vector \leftarrow 1. write PE
 2. $f = -\frac{\partial U}{\partial r}$ \rightarrow Scalar

gradient

$$f = -\frac{\partial U}{\partial r}$$

$$= -\frac{\partial}{\partial r} \left(-\frac{Gm_1 m_2}{r} \right)$$

'attractive'

$$= Gm_1 m_2 \frac{\partial}{\partial r} r^{-1}$$

$F = -\frac{Gm_1 m_2}{r^2}$

Class - VI



$$f = \frac{Gm_1 m_2}{r^2}$$

$f = +ve$ Repulsion



$$PE - U = -\frac{Gm_1 m_2}{r}$$



attrad

$$F = -\frac{6kP_1P_2}{r^4} \quad F_C = -P_2 \frac{2kP_1}{r^3} \cos\theta$$

$$F = \frac{6kP_1P_2}{r^4} \quad U = -\frac{2kP_1P_2 \cos\theta}{r^3}$$

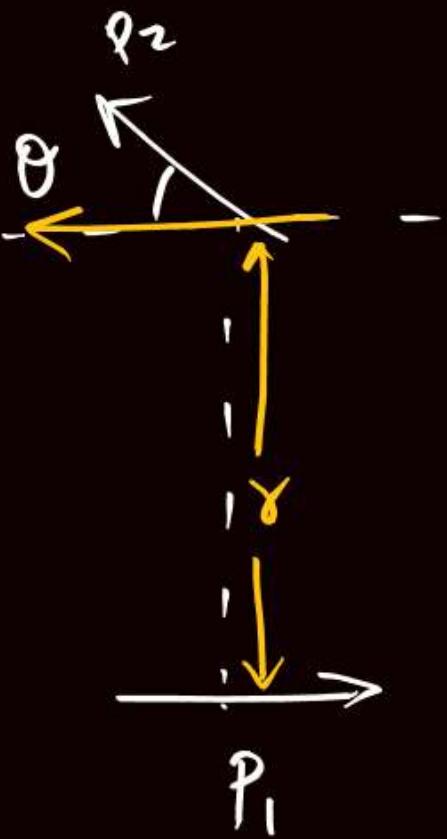
depel

$$F = -\frac{\partial U}{\partial r} = -\frac{\partial}{\partial r} \left(-\frac{2kP_1P_2 \cos\theta}{r^3} \right) = -\frac{6kP_1P_2 \cos\theta}{r^4}$$

force is position
& orientation

dependent

$$\epsilon = \frac{K P_1}{r^3}$$



$$P\cdot\vec{\epsilon} = -\vec{P}\cdot\vec{\epsilon} = -P\epsilon \cos\theta.$$

$$P\cdot\epsilon = -P_2 \frac{K P_1}{r^3} \cos\theta$$

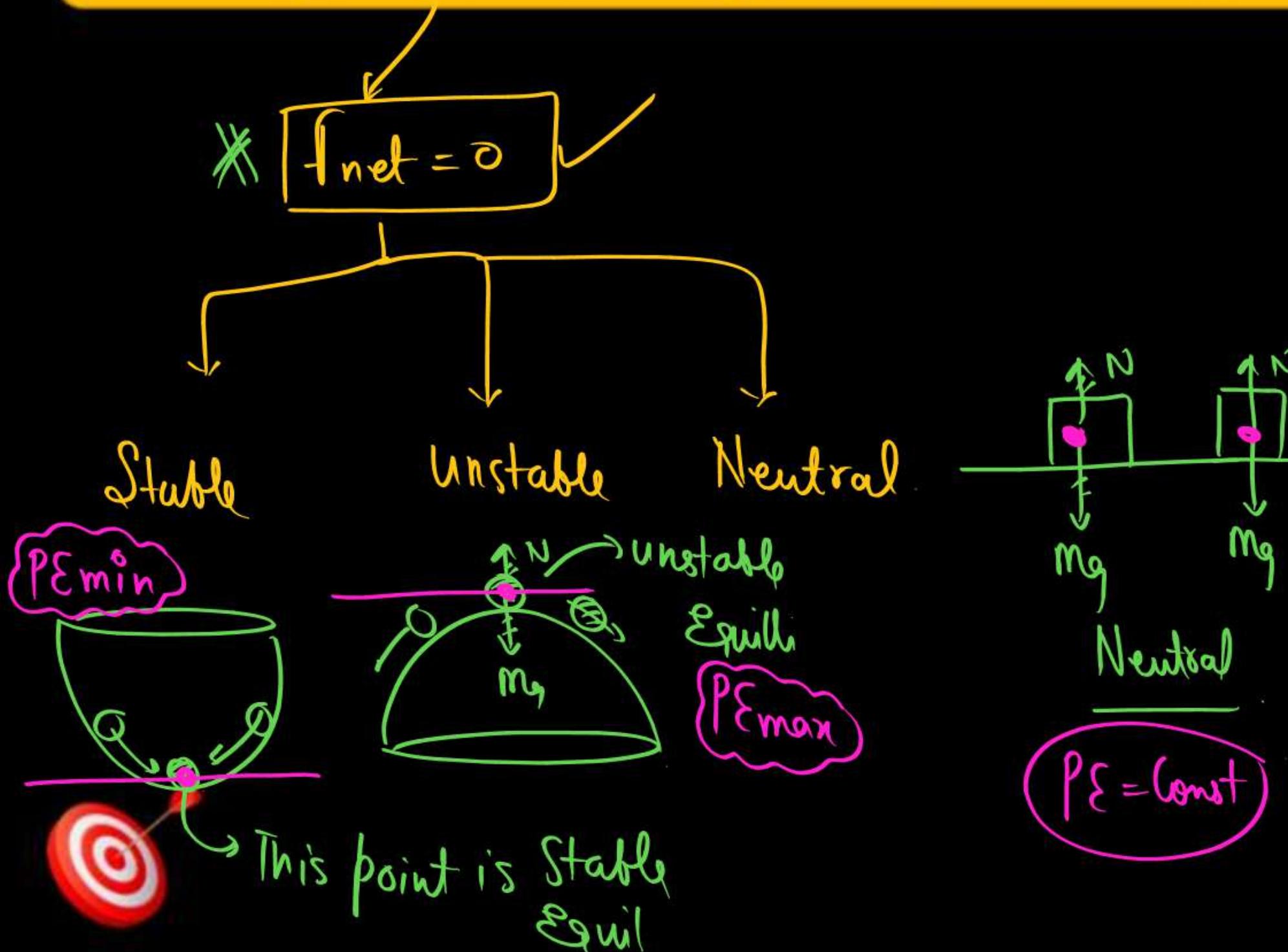
$$f = -\frac{\partial V}{\partial r}$$

$$= - \left(- K P_1 P_2 \cos\theta \right) \frac{\partial}{\partial r} r^{-3}$$

force between dipoles?

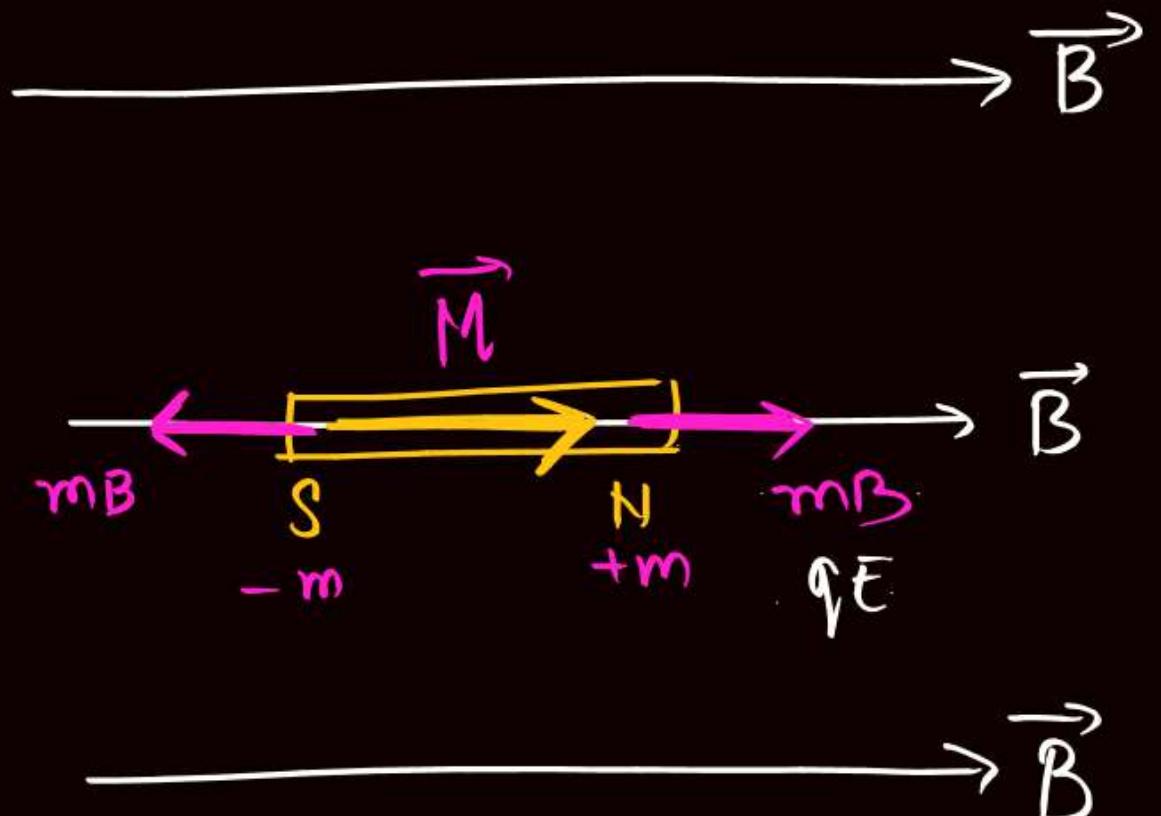
$$F = - \frac{3 K P_1 P_2 \cos\theta}{r^4}$$

Equilibrium positions and Oscillation



Ps dipole in Equilibrium

uniform B $f_{\text{net}} = 0$



"Stable"

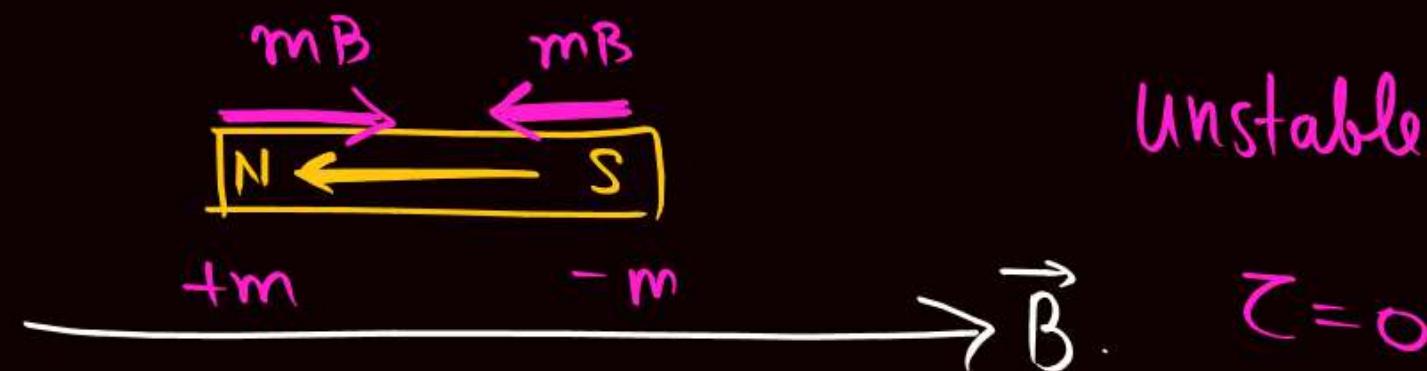
$$\begin{aligned} \tau &= \bar{M} \times \bar{B} \\ &= MB \sin \theta \\ &= 0 \end{aligned}$$

$$PE = -\bar{M} \cdot \bar{B}$$

$$= -MB \cos \theta$$

$$\boxed{PE = -Ve}$$

Stable



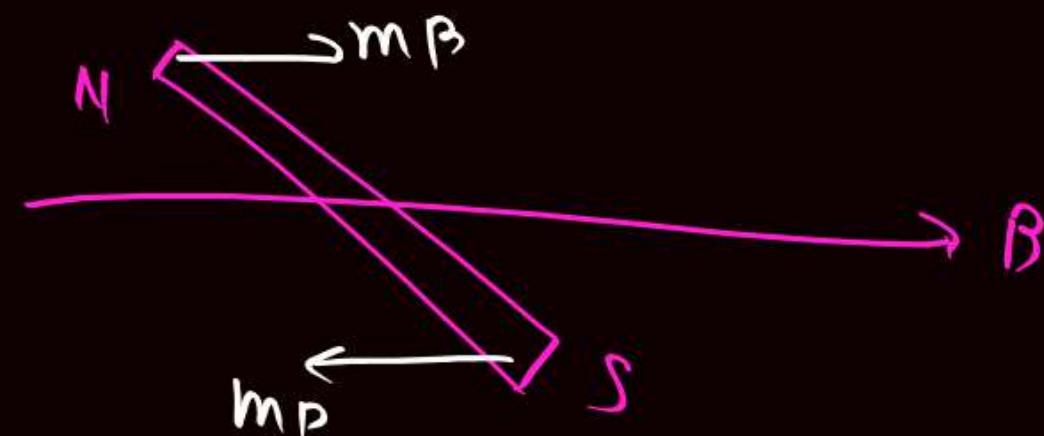
Unstable

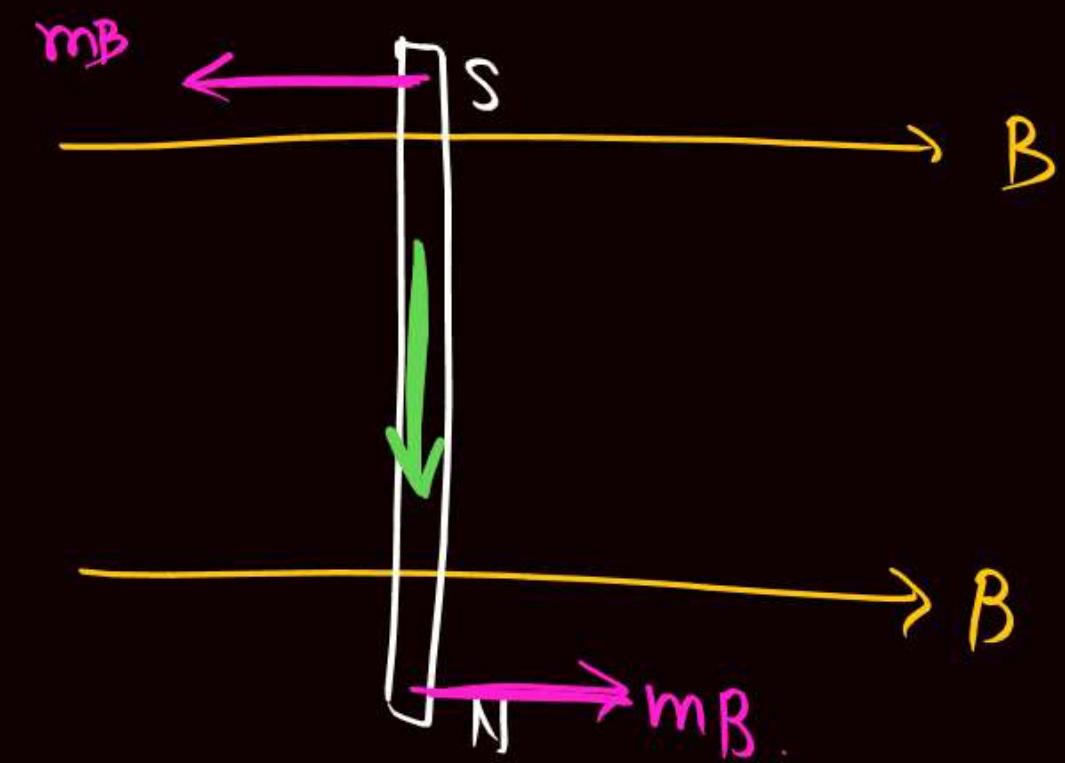
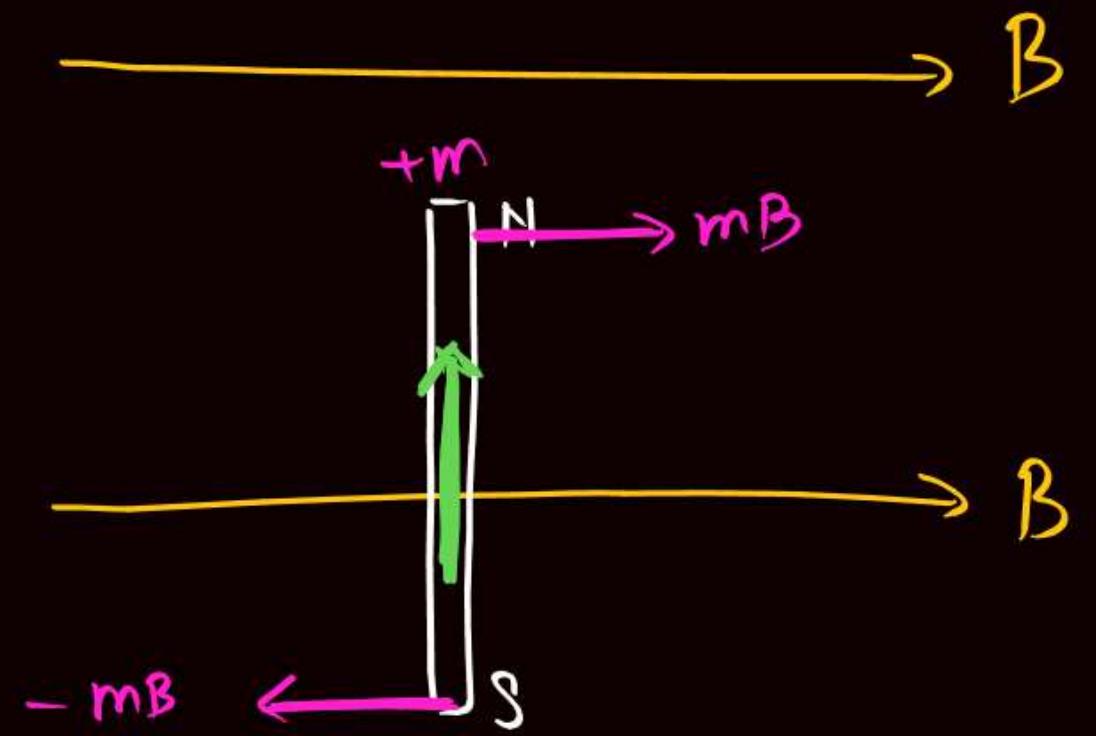
$$\tau = 0$$

$$PE = -\bar{M} \bar{B}$$

$$= -MB \cos 180^\circ$$

$$= +Ve \text{ (unstable)}$$





Equilibrium type

Not in
Equilibrium

$$f_{\text{net}} = 0$$

$$\tau_{\text{net}} \neq 0$$

$$\vec{\tau} = \vec{M} \times \vec{B}$$

$$\begin{aligned}\tau_1 &= -MB \sin 90^\circ \hat{k} \\ &= -MB \hat{k}\end{aligned}$$

$$\begin{aligned}\tau_2 &= +MB \sin 90^\circ \hat{k} \\ &= +MB \hat{k}\end{aligned}$$

$$\vec{\tau}_1 =$$

$$\vec{\tau}_1 \neq \vec{\tau}_2$$

$$|\vec{\tau}_1| = |\vec{\tau}_2|$$

Time Period of oscillation





Thank You Lakshyians