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| 1. | The sequence of merge sort algorithm is: | |
|-----|---|-----|
| | a. Divide Combine-Conquer | |
| | b. Conquer-Divide-Combine | |
| | c. Divide-Conquer-Combine Page 27 | |
| | d. Combine-Divide-Conquer | |
| 2. | In Knapsack Problem, limitation is that an item can eit | her |
| | be put in the bag or not. Fractional items are not allowed. | |
| | a. 0 | |
| | b. 1 | |
| | c. 0/1 Page 91 | |
| | d. Fractional | 1 |
| 3. | In Selection algorithm, we assume pivot selection takes theta | 1 |
| 1 | running time. | 1 |
| | a. n Page - 36 | 1 |
| A4 | b. n2 | |
| Y | c. n3 | |
| | d. log (n) | |
| 4. | In Heap Sort algorithm (using max heap), when every time | |
| | maximum elements removed from top | |
| | a. We call merge Sort Algorithm | |
| | b. it becomes Order n2 Algorithm | |
| | c. Divide and Conquer strategy helps us | |
| | d. We are left with a hole Page – 41 | |
| 5. | | |
| | q x r, then each entry in resultant matrix takes time. | |
| | a. O (q) Page - 84 | |
| | a. O (q) Page - 84 b. O (1) c. O (p x q) d. O (q x r) | |
| | c. O (p x q) | |
| | d. O (q x r) | |
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|------------|---|
| 6. | is a method of solving a problem in which we check all |
| | possible solutions to the problem to find the solution we need. |
| | a. Plane-Sweep Algorithm |
| | b. Sorting Algorithm |
| | c. Brute-Force Algorithm google |
| | d. Greedy approach |
| 7 . | The worst case running time of Quick sort algorithm |
| | a. Cannot be quadratic |
| | b. Is quadratic |
| | c. Is always Exponential |
| | d. Is linear |
| 8. | In max heap (for Heap Sort algorithm), when every time maximum |
| 4 | element is removed from top we replace it with leaf in the tree. |
| 1 | a. second last |
| A | b. Last Page -41 |
| Ž, | c. First |
| | d. Any |
| 9. | Quick sort algorithm was developed by - |
| | a. AlferdAho |
| | b. Sedgewick |
| | c. John Vincent Atanasoff |
| | d. Tony Hoare – Google wikipedia |
| 10 | . If Matrix-A has dimensions "3x2" and Matrix-B has dimensions |
| | "2x3", then multiplication of Matrix-A and Matrix-B will result a |
| | new Matrix-C having dimensions. |
| | a. 3x2 |
| | b. 2x3 c. 2x2 |
| | |
| | d. 3x3 http://www.calcul.com/show/calculator/matrix-multiplication |
| 11 | . For comparison-based sorting algorithms, it is possible to sort more efficiently than Omega n log(n) time. |
| | a. Always |
| | a.,a, o |

b. Not

c. Sometimes

| d. Sometimes not |
|---|
| 12. Dynamic Programming approach is usually useful in solving |
| optimization problems. |
| a. True |
| b. False |
| 13. In Sorting the key value or attribute from an ordered domain. |
| a. Must be page 39 |
| b. Not always |
| c. May be |
| d. Occasionally |
| 14. Result of asymptotical analysis of n(n -3) and 4n*n is that |
| a. n(n-1) is asympt <mark>oti</mark> cally Less |
| b. n(n-1) is asymp <mark>totically Greater</mark> |
| c. Both are asymptotically Not equivalent |
| d. Both are asymptotically Equivalent page 23 (4n*n= 4n²) |
| 15. Floor and ceiling are to calculate while analyzing |
| algorithms a. Very easy |
| b. Usually considered difficult P-31 |
| c. 3rd Option is missing |
| d. 4th Option is missing |
| 16 of reference is an important fact of current processor technology. |
| a. Defining |
| b. Assigning |
| c. Formality |
| d. Locality |
| 17. In max-heap, largest element is stored at root node. Where is |
| the smallest element stored? a. Right Node b. Leaf Node |
| a. Right Node |
| b. Leaf Node |
| c. Middle Node |
| d. Left Node |
| |

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| 18. In average-case time analysis of Quick sort algorithm, the most balanced |
| case for partition is when we divide the list of elements into |
| a. Equal no. of pieces as of input elements |
| b. Single piece exactly |
| c. Two nearly equal pieces |
| d. Three nearly equal pieces |
| 19. Which of the following is calculated with Big O notation? |
| a. Medium bounds |
| b. Upper bounds Page - 25 |
| c. Lower bounds |
| d. Both upper and lower bounds |
| 20. Edit distance algorithm based on strategy |
| a. Greedy |
| b. Dynamic Programming Page - 81 |
| c. Divide and Conquer |
| d. Searching |
| 21. In Heapsort Algorithm, total time taken by heapify procedure is |
| a. O (log n) Page-43 |
| b. O (log2 n) |
| c. O (n log n) |
| d. O (n2 log n) 22. Al-Khwarizmi was a/an |
| a. Artist |
| b. Mathematician P-7 |
| c. Astronomer |
| d. Khalifah |
| 23. When matrix A of 5x3is multiply with metric B of 3x4 then the |
| number of multiplication required is: Not found exactly |
| a. 15 |
| b. 12 |
| c. 36 |

Not Found exactly but as per formula at page 84,

d. 60

AL-JUNAID TECH INSTITUTE 24 Pseudo code of algorithms are to be read by

| 24. PS6 | eudo code of algorithms are to | o be read by |
|----------|--|---|
| a | ı. People | Page -12 |
| b | o. RAM | |
| С | . Computer | |
| d | I. Compiler | |
| | TO THE | here the number of sub-problems is Just |
| _ | i. 1 | P-34 |
| C | o. 2 s. 3 | 10/77 |
| d | l. 4 | |
| 26. Whe | en a recursive algorithm revisits t | the same problem over and over |
| agai | n, we say that the optimization p | robl <mark>em h</mark> as sub-problems. |
| W a | ı. Overlapping – Go | oogle Search |
| Vy b | o. Over costing | |
|) c | c. Optimized | V |
| d | I. Three | |
| 27. Siev | e technique is <mark>very</mark> important speci | al case of Divide-and-Conquer strategy. |
| a | ı. True | P-34 |
| b | o. False | |
| 28. In o | rder to say anything meaning | gful about our algorithms, it will |
| be i | mportant for us to settle on a | <u> </u> |
| а | . Java Program | |
| b | o. C++ Program | |
| С | . Pseudo program | 1659294 |
| d | I. Mathematical model of com | putation P-10 |
| 29. Mer | ge sort is based on | shelp.com |
| а | . Brute-force | 1 210 |
| b | o. Plan-sweep | shell |
| С | . Axis-sweep | |
| d | I. Divide and Conquer | P-27 |
| | | |
| | | |

| 30. What time does Merge Sort algorithm take in order to sort an | _ |
|---|----|
| array of 'n' numbers? | |
| a. (n) | |
| b. (log n) | |
| c. (n^2) | |
| d (n la m m) Canada Canada 24 la Mara Cant | |
| d. (n log n) Google Search 31. In Heap Sort | |
| 31. algorithm, the first step is to | |
| a. Call Build-Heap procedure Page - 46 | |
| b. Sort the array in descending order | |
| c. Call Heapify procedure | |
| d. Find the number of input elements 32. The definition of theta-notation relies on proving asymptotic bound. | À |
| 32. The definition of theta-notation relies on proving asymptotic bound. a. One | |
| b. Lower | b |
| | ζ, |
| c. Upper d. Both lower & upper Page - 25 | |
| d. Both lower & upper Page - 25 33. In merge sort algorithm, to merge two lists of size n/2 to a list of size n, take | • |
| time. | 3 |
| a. Theta (n) Page - 32 | |
| b. Theta log(n) | |
| c. Theta log2(n) | |
| d. Theta n log(n) | |
| 34. We can make recursive calls in Fibonacci Sequence. | |
| a. Infinite (1997) 3 (14-16-59) 9 4 | |
| b. Finite google | |
| b. Finite google c. Only one d. Zero | |
| d. Zero | |
| 35. Following is NOT the application of Edit Distance problem. | |
| a. Speech recognition | |
| b. Spelling Correction | |
| c. Ascending Sort Page - 76 | |
| d. Computational Molecular Biology | |
| | |

| | ,,, |
|---|------------------------------|
| 36. In plane sweep approach, a vertical lin | ne is swept across the 2d- |
| plane and structure is used for holdin | g the maximal points lying |
| to the left of the sweep line. | |
| a. Array | |
| b. Queue | |
| c. Stack | Page - 18 |
| d. Tree | 1 17 |
| 37. When a heapify procedure is applied to | the root node to restore the |
| heap, then at each level, the compariso | |
| a. It will take (log n). | 1/2 |
| b. It can not be predicted | 1/2 |
| c. It will take O (1). | Page - 43 |
| d. Time will vary according to the r | |
| 38 time is the maximum running ti | |
| a. Worst-case | Page - 13 |
| b. Average-case | |
| c. Best-case | |
| d. Good-case | |
| 39. Efficient algorithm requires less comp | outational |
| a. Memory | |
| b. Running Time | |
| c. Memory and Running Time | Page - 9 |
| d. Energy | |
| 40. For average-case time analysis of Qui | ick sort algorithm, Pivot |
| selection is on average basis from | 59794 |
| a. half of the input values | 11 |
| b. all possible random values | Page - 50 |
| c. Pivot is input separately | 10.0 |
| d. values greater than 5 | ell |
| 41. Selection algorithm takes theta | |
| a. (n2) | |
| b. (n) | Page - 37 |
| c. log(n) | |
| d. n log(n) | |

| 42. Recurrence can be described in terms of a tree. | | | |
|--|--|--|--|
| a. Yes Page - 31 | | | |
| b. No | | | |
| 43. Time complexity of Dynamic Programming based algorithm for | | | |
| computing the minimum cost of Chain Matrix Multiplication is | | | |
| a. Log n | | | |
| b. n | | | |
| c. n^2 (n square) | | | |
| d. n^3 (n cube) Page -90 | | | |
| 44. The Iteration method is used for | | | |
| a. Comparing sorting algorithms only | | | |
| b. Solving Recurrence relations Page 31 | | | |
| c. Merging elem <mark>ents</mark> in Merge sort | | | |
| d. Dividing ele <mark>ments</mark> in Merge so <mark>rt</mark> | | | |
| 45. In 3-Dimensional space, a point P has coordinate(s). | | | |
| a. (X, Y) | | | |
| b. (X, 0) | | | |
| c. (0, Y) | | | |
| d. (X,Y, Z) | | | |
| 46. Chain matrix multiplication problem can be solved through strategy. | | | |
| a. Dynamic programming Page - 85 | | | |
| b. Greedy | | | |
| c. Divide and conquer | | | |
| d. Sorting | | | |
| 47. Merge sort have running timerunning time of Heap sort. Not found exactly | | | |
| a. Greater than | | | |
| b. Less than Google | | | |
| c. Equal to | | | |
| d. Different than | | | |
| 48. Median is not useful measure of central tendency of given input | | | |
| set especially when the distribution of values is highly skewed. | | | |
| a. True | | | |
| b. False Page – 34 | | | |

| based sorting algorithms always takes Omega nlog (n) time. | | | |
|--|---|----------------------------|--|
| a. True | | (pg 46 not very clear) | |
| b. False | | (pg is not toly clour) | |
| | notation allows us to state only the a | asymptotic bounds. | |
| a. Midd | le TIOT | | |
| b. Lowe | r Page 25 | Th. | |
| c. Uppe | | 11/10- | |
| d. Both | lower & upper | TIVITA | |
| 4 190 | r & upperSorting can be in | | |
| a. Incre | asing order only | 4/7 | |
| b. Decre | easing order only | - // | |
| | Increasing and Decreasing ord lom order | er GOOGLR Search | |
| 52. Radix sort | performs sorting the numbers | digit (s) at a time. | |
| a. One | Pa | <mark>age - 71</mark> | |
| b. Two | | | |
| c. Three | 9 | | |
| d. All | | | |
| 53. Quicksort is a/an and sorting algorithm. | | | |
| a. Not i | n place, not stable one | | |
| b. In pla | ice , not stable one | Page - 54 | |
| c. In pla | ace , stable one | | |
| d. Not i | n place , stable one | | |
| 54. Consider t | hree matrices X,Y,Z of dimension | ons 1x2, 2x3,3x4 | |
| respective | ly. The number of multiplication | ns of (XY) Z is: | |
| a. 18 | As per lecture slides | 001/ | |
| b. 32 | W. Will 1 a | 10.0 | |
| c. 24 | vulmshe | | |
| d. 30 | | | |
| 55. In Fibonac | ci Sequence, unnecessary repeti | tions do not exist at all. | |
| a. True | | | |
| b. False | Pa | <mark>age – 74</mark> | |
| | | | |

| 56. It is not a Fibonacci sequence . 1,1,1,2,3,5,8,13,21,34,55, | | |
|--|--|--|
| a. True Page - 73 | | |
| b. False | | |
| 57. Heap sort is a/ an and sorting algorithem. | | |
| a. Not in place, not stable one | | |
| b. In place , not stable one Page - 54 | | |
| c. In place , stable one | | |
| d. Not in place , stable one | | |
| 58. Identify the True Statement | | |
| a. The knapsack problem does not belong to the domain of | | |
| optimization problems. | | |
| b. The knapsack problem belongs to the domain of optimization | | |
| problems. Page - 91 | | |
| c. The Knapsack problem cannot be solved by | | |
| using dynamic programming | | |
| d. The knapsack problem is optimally solved by using | | |
| brute force algorithm. | | |
| 59. In Dynamic Programming, our approach is to | | |
| a. Develop the solution in a top-down fashion | | |
| b. Express the problem non-recursively | | |
| c. Build the solution in a bottom-up fashion Page - 75 | | |
| d. Input several sub-problems simultaneously | | |
| 60. Counting sort is suitable to sort the elements in range 1 to K; | | |
| a. K is large | | |
| b. K is small Page - 57 | | |
| c. K may be large or small | | |
| d. None | | |
| 61. We can multiply two matrices A and B only when they are | | |
| compatible which means | | |
| a. Number of columns in A must be equal to number of rows in B. | | |
| it seems Correct as per page 84 | | |
| b. Number of rows and columns do not matter | | |
| | | |

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|-----------|---|------------------------------|
| C. | Number of columns in A must be equal t | to number of columns in B |
| d. | . Number of rows in A must be equal | to number of rows in B |
| 32. Matr | rix multiplication is a (n) ope | eration. |
| a. | . Commutative | |
| b. | . Associative Page 1 | age 85 |
| C. | . Neither commutative nor associative | e |
| d. | . Commutative but not associative | Th. |
| 3. In Dy | ynamic Programming approach, solution | on is modified / changed |
| a. | . Always once | |
| b. | . At each stage google a | and wikipedia |
| | Only for specific problems | 1/7 |
| d. | . At 4 th stage only | - \ \ \ \ \ \ |
| 64. In Kn | napsack problem, the goal is to put items in | the Knapsack such that |
| the va | ralue of the items is subject to v | veight limit of knapsack. |
| a. | . Minimized | |
| b. | . Decreased | |
| C. | . Maximized Pa | <mark>age - 91</mark> |
| d. | . None of the given options | |
| 65. An ir | n-place so <mark>rti</mark> ng algorith <mark>m is</mark> one that __ | uses |
| addi | itional array for storage. | |
| a. | . Always | |
| b. | . Permanently | |
| C. | . Does not Pa | <mark>age - 54</mark> |
| d. | . Sometime | |
| 66. Mem | noization is a part of Dynamic Program | mming Strategy. |
| a. | . True Pa | <mark>age - 74</mark> |
| | . False | (0) |
| | trix A of dimension 2x4 is multiply with mat | rix B of dimension 4x3, then |
| the c | dimension of resultant matrix is N | ot found exactly |
| a. | . 2x4 | |

It seems correct as per second last Para of page 84

b. 4x3c. 3x4d. 2x3

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| 68. In Dynamic Programming a | pproach, we do not store the solution |
| to each sub-problem in cas | e if it reappears. |
| a. True | |
| b. False | Page - 75 |
| 69. Dynamic Programming is a p | problem-solving approach in which |
| a. Problem is solved in Z | 'ero time |
| b. Solution is developed | only at final stage |
| c. Both are correct | TICII IVC |
| d. Both are incorrect | google |
| 70. In Fibonacci sequence, each te | erm is calculated by previous terms. |
| a. Subtracting, Two | 17 |
| b. Adding, Three | |
| c. Adding, Two | Page - 73 |
| d. Multiplying, Two | |
| 71. Selection sort is not an in-p | lace sorting algorithm. |
| a. True | Page - 54 |
| b. False | |
| 72. If there are θ (n ²) entries in edit | distance matrix then the total running time is: |
| a. θ (n) | |
| b. θ (1) | |
| c. θ (n ²) | Page – 84 |
| d. θ (n logn) | |
| 73. The only way to convert a s | tring of i characters into the empty |
| string is with i deletions, re | presented as |
| a. E(0.j) =j | 14-1659294 |
| b. E(i.j) = 1 | Page - 78 |
| c. E(0.i) = j | CO2 |
| d. E (i.0)=l | |
| | ulation of the matrix chain multiplication |
| problem will store the solution | ons of each sub problem in an |
| a. Array | |
| b. Table | Page - 86 |
| c. Variable | |
| d. class | |

| 75. We can use the optimal substructure property to devise a |
|---|
| formulation of the edit distance problem. |
| a. Selective |
| b. Optimum |
| c. Iterative |
| d. Recursive Page - 78 |
| 76. Sorting is performed on the basis of |
| a. Computational resources |
| b. Asymptotic notation |
| c. Summation |
| d. Some key value of attribute page- 39 |
| 77. In Heap Sort algorithm, we call Build-heap procedure |
| a. Only once page 46 |
| b. Twice |
| c. Thrice |
| d. As many times as we need |
| 78. Radix sort is not a non-comparative integer sorting algorithm. |
| a. True Google Search |
| b. False |
| 79. In the statement "output P[1].x, P[1].y", the number of times |
| elements of P are accessed is |
| a. 1 |
| b. 2 page 14 |
| c. 3 |
| d. 4 (S)()3()4-1659294 |
| 80. The main purpose of mathematical analysis is measuring the required by the algorithm. |
| a. Space |
| b. Execution time |
| c. Inputs & outputs |
| d. Execution time and memory |
| a. Execution time and memory |
| |

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| 81 provides us more accurate result when input values a |
| not closer with each other |
| a. Average |
| <mark>b. Median</mark> P-34 |
| c. Mode |
| d. Mean |
| 82. The process of ends when you are left with such tiny |
| pieces remaining that it is trivial to solve them. |
| a. Brute-force |
| b. Plan-sweep |
| c. Divide and Conquer P-27 |
| d. Axis-sweep |
| 83 overcomes the limitations of by |
| working as per positional notations of numbers. |
| a. Counting sort, Radix sort |
| b. Radix sort, Counting sort P-71 |
| 84. Memorization is a part of Dynamic Programming strategy. |
| a. True |
| b. False |
| 85. Rank of an element can be defined as |
| a. One minus the number of elements that are smaller |
| b. Two plus the number of elements that are greater |
| c. One plus the number of elements that are smaller P-34 |
| d. Two minus the number of elements that are smaller |
| 86. If the time complexity of an algorithm is given by O (1), |
| then its time complexity would be a. Polynomial b. Exponential c. Constant - Wikipedia |
| a. Polynomial |
| b. Exponential |
| |
| d. Average |
| 87. Quick sort is a recursive algorithm. |

Wikipedia; Google

<mark>a. True</mark> b. False

| 88. The asymptotic growth of n(n+1)/2 is: |
|--|
| a. O(n ²) As the n^2 term has the largest contribution, the Big-O complexity is O(n^2) |
| b. O(n) |
| c. O(n+2) |
| d. O(n log n) |
| 89. Approach of solving geometric problems by sweeping a line |
| across the plane is called sweep. |
| a. Line |
| b. Plane Page 18 |
| c. Cube |
| d. Box |
| 90. As per algorithm of Dynamic Programing, we need to store |
| a. First sub-problem only |
| b. Best solution only |
| c. Intermediate sub-problems Pg:75 |
| d. Final solution only |
| 91. In Sieve technique, we solve the problem |
| a. In recursive manner Pg:34 |
| b. Non recursively |
| c. Using Merge Sort algorithm |
| d. Using Brute force technique |
| 92. One of the limitation in 0/1 knapsack is that an item can either be |
| in the bag or not. |
| a. Use |
| b. Put Pg:91 c. Move |
| d. Store |
| 93. Which one is not passed as parameter in Quick sort algorithm? |
| a. End of the array |
| b. Middle of the array |
| c. Array (containing input elements) Google |
| d. Start of the array |
| a. Start Start array |
| |

| 94. In the analysis of Selection | n algorithm, we get the convergent |
|----------------------------------|---|
| a. Harmonic | |
| b. Linear | |
| c. Arithmetic | |
| d. Geometric | Pg:37 |
| 95. A Random Access Mac | hine (RAM)is an idealized machine |
| withrandom access me | mory. |
| a. Infinite large | Pg:10 |
| b. 512 MB | |
| c. 256 MB | 1/7 |
| d. 2 GBs | 4/7 |
| 96. While analyzing Selection | on algorithm, we make a number of |
| passes, in fact it could | be as many as |
| a. n(n+1) | |
| b. log(n) | Pg:37 |
| c. n/3 | |
| d. n/4 | |
| | chine (RAM), instructions are executed in |
| a. Parallel | |
| b. Batch | |
| c. One by One | Pg:10 |
| d. Multiple times | |
| A Section 1 | ank of an element will be its position |
| a. First | 2211122201 |
| b. final | Pg:34 |
| c. Second last | |
| d. Last | CO112 |
| 99. The worst-case running | |
| sort an array of n eleme | ents. |
| a. O(log n) | |
| b. O(n) | |
| c. O(n log n) | page 40 and google |
| d. O(n) | |
| | |

| 100. | f(n) and g(n) are asymptotically equivalent. This means | | | |
|------|---|---|--|--|
| tl | hat they have essentially the same | | | |
| | a. Results | | | |
| | b. Variables | | | |
| | c. Size | | | |
| | d. Growth rates | | | |
| 101. | An algorithm is a mathematical entity. Which is independent of | | | |
| | a. Programming language | | | |
| | b. Machine and Programming language | | | |
| | c. Compiler and Programming language | | | |
| | d. Programming language Compiler and Machine P:07 | | | |
| 102. | In Quick sort algorithm, Pivots form | A | | |
| 1 | a. Stack | Þ | | |
| N | b. Queue | | | |
| A. | c. Binary Search Tree P:49 | P | | |
| Y | d. Graph | 1 | | |
| 103. | Counting sort is suitable for sorting the elements within range 1 to P. where | | | |
| | a. P is large | | | |
| | b. P is small P-57 | | | |
| | c. P is very large | | | |
| | d. P is undetermined | | | |
| 104. | In asymptotical analysis of n'(5 2)-3, as n becomes large, | | | |
| tl | he dominant (fastest growing) term is some constant times | | | |
| | a. n_1 | | | |
| | b. n (S)()3()4-1659794 | | | |
| | c. n+1 | | | |
| | d. n*n P-23 | | | |
| 105. | c. n+1 d. n*n P-23 Items are not allowed in the 0/1 | | | |
| | knapsack. a. Lighter | | | |
| | b. Fractional P-91 | | | |
| | c. Whole | | | |
| | d. Weighty | | | |
| | | | | |
| | | | | |

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| | _ | | _ | |

| 106. | Fibonacci Sequence was nar | ned on | _, a famous |
|------|--------------------------------------|------------------|------------------|
| m | athematician in 12th Century | | |
| | a. Fred Brooks | | |
| | b. Grady Booch | | |
| | c. Leonardo Pisano | P-73 | |
| | d. Edgar F. Codd | OTT | |
| 107. | In Heap Sort algorithm, we be | uild for | ascending sort. |
| | a. Max heap | P-41 | Non |
| | b. Min heap | | 10/12 |
| 108. | Bubble sort is not an in-place | e sorting algo | rithm. |
| A | a. True | | 4/7 |
| 2 | <mark>b. False</mark> | P-54 | |
| 109. | In partition algorithm, the su | barray | has elements |
| W | hich are greater than pivot ele | ement x. | |
| NA | a. A[pr] | | |
| Y | b. A[pq-1] | | |
| | c. A[q] | | |
| | d. A[q+1r] | P-46 | |
| 110. | In Heap Sort algorithm, if heap prop | erty is violated | |
| | a. We call Build heap proced | lure P-43 | |
| | b. We call Heapify procedure | θ / | |
| | c. We ignore | | |
| | d. Heap property can never | be violated | |
| 111. | is not a characteristic | of Random A | Access Machine. |
| | a. Single-Processor P- | 10 659 | 194 |
| | b. Assigning a value to a va | riable | 1.CO111 |
| | c. Locality of reference | | 00% |
| | d. Executing an arithmetic in | | |
| 112. | The only way to convert an e | mpty string ir | nto a sting of j |
| C | haracters is by doing j inserti | ons, represen | ted as |
| | a. E(i,j) = 1 | | |
| | b. E(I,0) = I | | |
| | c. E(0,j) = j page 78 | | |
| | d. E(1,j)= j | | |
| | | | |

| 113. In Selection problem, the Sieve technique works in |
|--|
| a. Non-recursive manner |
| b. Constant time |
| c. Phases page 34 |
| d. One complete go |
| 114. Algorithm is a sequence of computational steps that |
| the input into output. |
| a. Merge |
| b. Assign |
| c. Transform page 7 |
| d. Integrate |
| 115. If pj dominates pi and pi dominates ph then pj also dominates |
| ph, it means dominance relation is |
| a. Transitive page 18 |
| b. Non Transitive |
| c. Equation |
| d. Symbolic |
| 116. To find maximal points in brute-force algorithm each point of |
| the space is compared against of that space. |
| a. One other point |
| b. All other points page 11 |
| c. Few other points |
| d. Most of the other points |
| 117. In the following code the statement "cout< <j;"executes< td=""></j;"executes<> |
| times. for (j=1; j<=5; j = j+2) |
| cout< <j;< td=""></j;<> |
| a. 5 times |
| b. 2 times |
| times. for (j=1; j<=5; j = j+2) cout< <j; 2="" 3="" 5="" a.="" b.="" c.="" td="" times="" times<=""></j;> |
| d. 0 times |
| |
| |

| 118. In merge sort algorithm, we split the array around the |
|--|
| index q. a. Entring |
| b. Mid page 17 |
| c. Exiting |
| d. Summing |
| 119. In Selection problem, the Sieve technique |
| a. Add some more input items each time |
| b. Do not work recursively |
| c. Do not uses Divide and Conquer approach |
| d. Eliminates undesired data items each time |
| 120. Consider three matrices X, Y, Z of dimensions 1 x 2, 2 x 3, |
| 3 x 4 respectively. The number of multiplications of X(YZ) is . |
| a. 16 |
| b. 32 |
| c. 26 |
| d. 32 page 84 |
| 121. In Heap Sort algorithm, the total running time for Heapify procedure is |
| |
| a. Theta (log n) |
| b. Order (log n) |
| c. Omega (log n) |
| d. O(1) i.e. Constant time |
| 122. The sieve technique works where we have to find |
| items(s) from a large input. |
| a. Single page 34 |
| b. Two c. Three d. Similar |
| c. Three |
| |
| 123. In Dynamic Programming based solution of Knapsack Problem, |
| if we decide to take an object i , then we gain |
| a. W(Total Weight of Knapsack) |
| b. V (Total Value of all items) |
| c. vi (Value of object i) page 93 |
| d. Nome of the given option |
| |

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| 124. | While Sorting, the order domain means for any two input elements x and y |
| | satisfies only. |
| | a. x < y page 39 |
| | b. x > y |
| | c. x = y |
| | d. All of the above |
| 125. — | For solving Selection problem, we introduced Sieve technique due to |
| | a. Using Decrease and Conquer strategy page 34 |
| | b. Avoiding to sort all input data |
| | c. Eliminating Rank of an element |
| | d. Using Brute-force approach |
| 126. | is one of the few problems, where provable lower |
| b | ounds exist on ho <mark>w fas</mark> t we can sort. |
| N. | a. Searching |
| (4 | b. Sorting page 38 |
| 7 | c. Both Searching & sorting |
| | d. Growing |
| 127. | In plane sweep approach, a vertical line is swept across |
| tł | ne 2d-plane from |
| | a. Right to Left |
| | b. Left to Right page 18 |
| | c. Top to Bottom |
| | d. Bottom to top |
| 128. | In generating Fibonacci sequence, we can avoid unnecessary repetitions by |
| _ | process |
| | a. Tokenization |
| | b. Memorization page 43 |
| | a. Tokenization b. Memorization c. Randomization d. Memorization |
| | d. Memorization |
| 129. | |

page 14

a. Small

c. Large d. Infinity

b. Medium

| 130. Dynamic programming comprises of |
|---|
| a. Recursion only |
| b. Repetition only |
| c. Recursion with Repetition |
| d. No Repetition but Recursion page 75 |
| 131. The function f(n)=n(logn+1)/2 is asymptotically equalient t nlog n :Here Lower |
| Bound means function f(n) grows asymptotically at as fast as nlog n. |
| a. Least page 23 |
| b. Normal |
| c. Most |
| d. At |
| 132. Counting sort has time complexity. |
| a. O(n+k) |
| b. O(n) page 58 |
| c. O(k) |
| d. O(nlogn) |
| 133. Due to left complete nature of binary tree, the heap can be stored in |
| a. Array page 40 |
| b. Structures |
| c. Link List |
| d. Stack |
| 134. Single item from a larger set of |
| a. Constant |
| b. Pointers |
| c. Phases (S)()3()4-(659)94 |
| d. n items page 34 |
| 135. In the clique cover problem, for two vertices to be in the same |
| group, they must be each other. |
| a. Apart from |
| b. Far from |
| c. Near to |
| d. Adjacent to page 76 |
| |
| |

| 136. How much time merge sort takes for an array of numbers? | |
|---|----|
| a. T(n^2) | |
| b. T(n) | |
| c. T(log n) | |
| d. T(n log n) page 40 | |
| 137. In in-place sorting algorithm is one that uses arrays for storage. | |
| a. No additional array page 54 | |
| b. An additional array | |
| c. Both of above may be true according to algorithm | |
| d. More than 3 arrays of one dimension | |
| 138. Brute-force algorithm for 2D-Maxima is operated by comparing | |
| pairs of points. | 1 |
| a. Two | |
| b. Some | ٧. |
| c. Most | 1 |
| d. All page 18 | |
| 139. While Sorting, the ordered domain means for any two input | |
| elements x and y satisfies only. | |
| a. x > y | |
| b. x < y | |
| c. x = y | |
| d. All of the above page 38 140. Quick sort is. | |
| | |
| a. Stable & in place | |
| b. Not stable but in place page 54 c. Stable but not in place | |
| d. Some time stable & some times in place | |
| c. Stable but not in place d. Some time stable & some times in place 141. Which may be a stable sort? a. Merger | |
| a. Merger | |
| b. Insertion | |
| c. Both above page 54 | |
| d. None of the above | |
| | |
| | |

| 142. | For the Sieve Technique we take time. |
|------|---|
| | a. T(nk) page 34 |
| | b. IT(n / 3) |
| | c. n^2 |
| | d. n/3 |
| 143. | Continuation sort is suitable to sort the elements in range 1 to k. |
| | a. K is Large |
| | b. K is not known |
| | c. K may be small or large |
| | d. K is small page 54 |
| 144. | Asymptotic growth rate of the function is taken over |
| | se running time |
| 1 | a. Best |
| | b. Worst page 14 |
| MA. | c. Average |
| 7 | d. Normal |
| 145. | The sieve technique is a special case, where the number of |
| su | ıb problems is just. |
| | a. 5 |
| | b. Many |
| | c. 1 page 34 |
| | d. Few |
| 146. | In Quick sort, we don't have the control over the sizes of recursive calls. |
| | a. True page 49 |
| | b. False (5) 3 4 - 6 5 9 7 9 4 |
| | c. Less information to decide |
| | d. Ether true or false |
| 147. | Before sweeping a vertical line in plane sweep approach, in start sorting |
| of | the points is done in increasing order of their coordinates |
| | a. X page 18 |
| | b. Y |
| | c. Z |
| | d. X , Y |
| | |
| | |

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|--------------------------|--|
| 148. | Random access machine or RAM is a/an. |
| | a. Machine build by Al-Khwarizmi |
| | b. Mechanical machine |
| | c. Mathematical model page 10 |
| | d. Electronics machine |
| 149. | The Huffman codes provide a method of encoding data |
| ir | nefficiently when coded using ASCII standard. |
| | a. True |
| | b. False page 99 |
| 150. | A heap is a left-complete binary tree that confirms to the |
| | a. increasing order only |
| | b. decreasing order only |
| 4 | c. heap order page 40 |
| | d. log n order |
| 151. | If we associate (x, y) integers pair to cars where x is the speed of the car and |
| Уу | is the negation of the price. High y value for a car means a car. |
| 7 | a. Fast |
| | b. Slow |
| | c. Expensive |
| | d. Cheap |
| 152. | Which one of the following sorting algorithms is the fastest? |
| | a. Merge sort |
| | b. Quick sort |
| | c. Insertion sort |
| | d. Heap sort |
| 153. | Quick sort algorithm divide the entire array into sub arrays. |
| | a. 2 |
| | a. 2 b. 3 c. 4 d. 5 |
| | c. 4 VIII mahell |
| | d. 5 |
| 154. | In brute force algorithm, we measure running time T(n) based on |
| | a. Average-case time and best-case time |
| | b. Worst-case time and average-case time page 46 |
| | c. Worst-case time and best-case time |
| | d. Best-case time and staring-case time |

| 155. | For 2D Maxima problem. Plane Sweep algorithm first of all |
|------|--|
| | a. Sorts all points |
| | b. Delete some points |
| | c. Output the elements |
| | d. Pushes all points on stack |
| 156. | There are entries in the Edit Distance Matrix |
| | a. e (n) |
| | b. ө (n₂) |
| | c. e (n+2) |
| | d. e (n + 100) |
| 157. | Which symbol is used for Omega notation? |
| yı. | a. (O) |
| 1 | b. (e) |
| V | <mark>c. (Ω)</mark> |
| MA | d. (@) |
| 158. | Selection sort is a sorting algorithm |
| | a. In-place page 54 |
| | b. Not In-Place |
| | c. Stable |
| | d. in-partition |
| | In Dynamic Programming based solution of knapsack problem, |
| to | compute entries of 'V', we will imply a(n) approach. |
| | a. Subjective |
| | b. Inductive |
| | c. Brute Force |
| | d. Combination |
| 160. | We do not need to prove comparison-based sorting |
| а | lgorithms by mathematically. It always takes time. |
| | a. Big Oh nlog(n) |
| | b. Omega nlog(n) NOT SURE |
| | c. Omega n(n^2) |
| | d. Theta nlog(n) |
| | |
| | |

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| 161. Merge sort is a/an and sorting algorithm |
| a. Not in-place, not stable one |
| b. In-place, not stable one |
| c. In-place, stable one |
| d. Not in-place, stable one page 54 |
| 162. Cubic function will a quadratic function. |
| a. Prove |
| b. be equal to |
| c. overtake Page 25 |
| d. find |
| 163. Insertion sort is a sorting algorithm |
| a. Unstable |
| b. In-place Page 54 |
| c. Not In-Place |
| d. in-partition |
| 164. To check whether a function grows faster or slower than the other |
| function, we use some asymptotic notations, which is |
| a. Big-oh notation |
| b. Theta notation |
| c. Omega notation |
| d. All of the given 165. Asymptotic growth of 8n^2 + 2n – 3 is: |
| a. $\Theta(n^2 + n)$ |
| |
| b. Θ (n^2) page 14 c. Θ(8n^2) 4 – (Δ – |
| d. Θ(8n^2 + 2n) |
| 166. In the analysis of algorithms, plays an important role. |
| a. text analysis |
| b. time |
| c. growth rate |
| d. money |
| |

| 167. | In inductive approach of knapsack problem, we consider 2 cases, |
|------|--|
| C | Or |
| | a. Median, Mode |
| | b. Recursive, Iterative |
| | c. Leave object, Take object page 93 |
| | d. Sequentially. Parallel |
| 168. | Random Access Machine (RAM) can execute instructions |
| | a. only logical |
| | b. parallel |
| | c. only arithmetic |
| | d. logical and arithmetic |
| 169. | Using algorithm, efficiency is not given much importance |
| | a. Greedy |
| N | b. Merge sort |
| A. | c. Processing as there is no algorithm by this name |
| Y | d. Brute Force |
| 170. | Bubble sort takes theta in the worst case |
| | a. (n2) page 39 |
| | b. (n) |
| | c. log(n) |
| | d. nlog(n) |
| 171. | If matrix A of dimension $p \times q$ is multiply with matrix B of |
| d | imension q × r, then dimension of resultant matrix is: |
| | a. p×q |
| | b. p × r page 84 4 - 16 5 5 2 5 4 |
| | c. q×r |
| | d. r×p |
| 172. | |
| _ | to store the results of intermediate sub-problems |
| | a. table (Page 75) |
| | b. variable |
| | c. stack |
| | d. loop |
| | |
| | |

| 73. | is in-place sorting algorithm. |
|------------|---|
| | a. Bubble sort (Page 54) |
| | b. Merge sort |
| | c. Linear search |
| | d. Binary Search |
| 74. | Which one of the following problems can be solved using dynamic problem? |
| | a. Bubble sort problem |
| | b. Matrix chain multiplication problem page 85 |
| | c. Greedy search problem |
| | d. Fractional knapsack problem |
| 75. | In chain matrix multiplication, solutions of the sub-problems are stored in a |
|) <u> </u> | |
| 1 | a. Array |
| V | b. Table page 86 |
| Y | c. Tree |
| Y | d. Link list |
| 176. | What is the average running time of a quick sort algorithm? |
| | a. O(n^2) |
| | b. O(n) |
| | c. O(n log n) (Page 49) |
| | d. O(log n) |
| | Sorting Algorithms having O running time are |
| C | onsidered to be slow ones. |
| | a. (n) |
| | b. (n^2) (Page 39) |
| | c. (nlog(n)) |
| | d. (log(n)) |
| 78. _ | While solving Selection problem, in Sieve technique we partition input data |
| | a. In increasing order |
| | b. In decreasing order |
| | c. According to Pivot |
| | d. Randomly |

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| 179 is the process of avoiding unnecessary repetitions |
| by writing down the results of recursive calls and looking them |
| up again if we need them later. |
| a. Loop |
| b. Memoization page 74 |
| c. Recursion |
| d. Function |
| 180. In average-case time the probability of seeing input is denoted by |
| a. p{I}- |
| b. p[l] |
| c. p <i></i> |
| d. p(i) page 13 |
| 181. While applying the Sieve technique to selection sort, how to |
| choose a pivot element. |
| a. Through mean |
| b. Linear |
| c. Randomly page 35 |
| d. Sequentially |
| 182. Number of of the pseudo code are counted to measure |
| the running time. |
| a. Inputs |
| b. Outputs |
| c. Steps page 13 |
| d. Pages |
| 183. Developing a dynamic programming algorithm generally involves |
| separate steps. |
| a. One b. Two page 75 c. Three d. Four |
| b. Two page 75 |
| c. Three |
| d. Four |
| 184. 8n^2+2n+3 will exceed c28(n), no matter how large we make |
| a. n |
| b. 2n |
| c. c2 page 25 |
| d, this quadratic equation |

| 185. | The running time of quick sort algorithm |
|------|---|
| | a. Is impossible to compute |
| | b. Has nothing to do with pivot selection |
| | c. Is Random upon each execution |
| | d. Greatly influenced by the selection of pivot page 49 |
| 186. | involves breaking up the problem into sub problems |
| W | hose solutions can be combined to solve the global problem. |
| | a. Complexity Theory |
| | b. Dynamic programming solution |
| | c. Divide and Conquer Strategy page 34 |
| 2 | d. Greedy Algorithms |
| 187. | In we have to find rank of an element from given input. |
| 1 | a. Merge sort algorithm |
| V | b. Selection problem page 34 |
| Ad | c. Brute force technique |
| Y | d. Plane Sweep algorithm |
| 188. | How many steps are involved to design the dynamic programming strategy? |
| | a. 2 |
| | b. 3 |
| | c. 1 |
| | d. 4 page 92 |
| 189. | In Bucket sort, if there are duplicates then each bin can be |
| | replaced by a a. Stack |
| | b. Linked list page 69 |
| | c. Hash table 0504-1659294 |
| | d. Heap |
| 190. | In merge sort algorithm, we split the array to find index q. |
| | a. from start W |
| | b. midway page 28 |
| | c. from end |
| | d. both from start or end |
| | |
| | |

191. Find the maximum value of the items which can carry using knapsack Knapsack weight capacity = 50.

Item Weight Value

11070

22020

33080

470 200

- a. 280
- b. 100
- c. 90
- d. 200
- 192. In 2-d maxima problem a point p is said to be dominated by point q if

a.
$$p.x \leq q.x$$

- b. p.x <= q.x and p.y <= q.y page 17
- c. p.y <= q.y
- d. $p.x \ge q.x$ and $p.y \ge q.y$
- 193. Sorting can be in _____
 - a. Increasing order only
 - b. Decreasing order only
 - c. Both increasing and decreasing order
 - d. Random order
- 194. Recurrence can be described in terms of
 - a. Array
 - b. Linear
 - c. Tree page 31
 - d. Graph
- 195. The brute-force algorithm for 2D-Maxima runs in order O(__) time.
 - a. n
 - b. n(log n)
 - c. n*n page 18
 - d. n3

| 196. | In plane sweep approach of solving geometric problems, a |
|------|---|
| _ | is swept across the plane. |
| | a. Line page 18 |
| | b. Plane |
| | c. Cube |
| | d. Box |
| 197. | Which of the following is calculated with Big Omega notation? |
| | a. Medium bounds |
| | b. Upper bounds |
| | c. Lower bounds Page - 25 |
| | d. Both upper and lower bounds |
| 198. | is always based on divide and conquer strategy. |
| 1 | a. Bubble sort |
| | b. Selection sort |
| A. | c. Pigeon sort |
| Y | d. Quick sort page 46 |
| 199. | If a matrix has three rows and two columns, then dimensions |
| 0 | f matrix will be: |
| | a. 3x2 |
| | b. 2x3 |
| | c. 3x3 |
| | d. 2x2 |
| 200. | Asymptotic notations are used to describe of an algorithm. |
| | a. Length |
| | b. running time google |
| | c. size |
| | c. size d. compile time |
| 201. | Catalan numbers are related the number of different on 'n' nodes. |
| | a. Arrays |
| | b. linked lists |
| | c. binary trees page 85 |
| | d. functions |
| | |

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| 202. Applying the sieve technique to selection problem, |
|--|
| element is picked from array. |
| a. Output |
| b. Total |
| c. Input |
| d. Pivot page 35 |
| 203. Dynamic Programming approach is usually useful in solving |
| problems. |
| a. Normal |
| b. Optimization google |
| c. Array |
| d. Loop |
| 204. In recursive formulation of knapsack |
| Problem: V [0, j] = for j>=0 |
| a1 |
| b. 0 page 93 |
| c. 1 |
| d. 2 |
| 205 is a linear time sorting algorithm. |
| a. Merge sort |
| b. Radix sort page 71 |
| c. Quick sort |
| d. Bubble sort |
| 206. Quick sort is one of the sorting algorithm. |
| a. Fastest page 19 |
| b. Slowest |
| b. Slowest c. Major d. Average |
| |
| 207. The time assumed for each basic operation to execute on |
| RAM model of computation is a. Infinite |
| |
| b. Continuous c. Constant page 10 |
| <mark>c. Constant </mark> |
| u. vai labi c |

| 208. In Sieve Technique, we know the item of |
|--|
| interest. a. True |
| b. False page 34 |
| 209. While analyzing algorithms, and usually |
| considered difficult to calculate. |
| a. Finite, Infinite |
| b. Floor, ceiling google |
| c. Row, Column |
| d. Graph, Tree |
| 210. While analysis of the brute-force maxima algorithm, an array |
| sorted in the reverse order is the type of case inpu |
| a. Best |
| b. Worst page 14 |
| c. Somewhat bad |
| d. Average |
| 211 is not useful measure of central tendency of given |
| input set especially when the distribution of values is highly skewed. |
| a. Mean |
| b. Mode |
| c. Average |
| d. Median page 34 212. In asymptotical analysis of n(n-3) and 4n*n, as n becomes large, |
| |
| the dominant (fastest growing) term is some constant times |
| a. n+1 |
| b. n-1 c. n <mark>d. n*n page 23</mark> |
| c. n |
| d. n*n page 23 |
| 213. In addition to passing in the array itself to Merge Sort |
| algorithm, we will pass in other arguments which are indices. |
| <mark>a. Two</mark> b. Three |
| c. Four |
| d. Five |
| u. i ive |

| 214. In 2d-maximal problem, | a point is said to be if it is not |
|--|--|
| dominated by any other p | oint in that space. |
| a. Member | |
| b. Minimal | |
| c. Maximal | P-11 |
| d. Joint | TOTA |
| 215. Counting sort assumes the | at the numbers to be sorted are in the range |
| a. K to n where n is lar | ge |
| b. 1 to k where k is sma | all (P-57) |
| c. K to n where k is sm | all |
| d. k to n where n is sm | all |
| 216. Insertion sort is an efficiency of electric number of electric nu | cient algorithm for sorting a ements |
| a. Large | P-39 |
| b. Small | |
| c. Extra large | |
| d. Medium | |
| 217. If the indices passed to | merge sort algorithm are |
| then this means that there | e is only one element to sort. |
| a. Small pa | <mark>age 28</mark> |
| b. Large | |
| c. Equal | |
| d. Not Equal | |
| | each item must be entirely accepted |
| or rejected, is called | problem. |
| a. Fractional | Imshelp.com |
| b. 0-1 P-92 | Imaha Di |
| c. Linear | Imsile |
| d. Optimal | |
| | |

| 219. If the time complexity of an algorithm is O(n). then it is called |
|--|
| time complexity. |
| a. Linear Wikipedia |
| b. Constant |
| c. Average |
| d. Exponential |
| 220. In the case of analysis does not depend upon on |
| the distribution of input. |
| a. Merge sort |
| b. Quick sort |
| c. Insertion sort |
| d. Heap sort |
| 221. We can use the Property to devise a recursive |
| formulation of the edit distance problem. |
| a. Small substructure |
| b. Algorithmic |
| c. Real |
| d. Optimal substructure page 78 |
| 222. The following sequence is called |
| 1,2,3,5,8,13 <mark>,21</mark> ,34,55, |
| a. Optimize sequence |
| b. Fibonacci sequence page 73 |
| c. Optimal sequence |
| d. Overlapping sequence |
| 223. Which one sorting algorithm is best suited to sort an array |
| of 2 million elements? |
| a. Bubble sort b. Insert sort c. Merge sort |
| b. Insert sort |
| c. Merge sort |
| u. Quick Soft |
| e. Ridx Sort page 71 |
| |
| |

| be able to _, |
|--|
| a. Skip input elements somehow |
| b. Select two or more pivots page 34 |
| c. Skip any sub-array completely |
| d. Eliminate recursive calls |
| 225. The problem with the brute-force algorithm is that is uses |
| in pruning out de |
| a. Worst-case time |
| b. No intelligence page 18 |
| c. Outside looping |
| d. Artificial intelligence |
| 226. In chain matrix multiplication, the order of the matrices |
| a. Can be changed |
| b. Can not be changed page 85 |
| c. is equal |
| d. is reverse |
| 227. In quick sort algorithm, we choose pivot |
| a. Always the smallest element |
| b. Greater than 5 |
| c. Randomly page 35 |
| d. Less than 5 |
| 228. In Heap Sort algorithm. Heapify procedure is in nature. |
| a. Recursive |
| b. Non-Recursive page 43 |
| c. Fast |
| d. Slow |
| 229. When matrix A of 5x 3 is multiplied with matrix B of 3 x 4 then |
| the number of multiplications required will be |
| a. 15 |
| b. 12 |
| c. 36 |
| <mark>d. 60</mark> |
| |

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| 230. | An algorithm is said to be correct if for every instance, |
| it | halts with the correct |
| | a. Input, Output page 13 |
| | b. Design, Analysis |
| | c. Value, Key |
| | d. Key, Analysis |
| 231. | In chain matrix multiplication, table is filled |
| to | o find the multiplication of matrix. |
| | a. row wise |
| A | b. column wise |
| 2 | c. diagonally |
| 1 | d. bottom-to-up page 86 |
| 232. | If we have an equation 8n2+7f*n + 5f + 6 then is large, term |
| W | ill be muchxxxxxxxthe n term and will dominate the running time. |
| Y | a. f g (n) |
| | b. g (n) * 2 |
| | c. n * 2 page 23 |
| | d. f (n) |
| 233. | For quick sort algorithm. Partitioning takes theta |
| | a. (n) |
| | b. log(n) |
| | c. n log (n) |
| | d. n2log (n) |
| 234. | In Heap Sort algorithm, the maximum levels an element can move upward is |
| _ | |
| | a. Theta (log n) page 43 b. Big-ch (log n) c. Omega (log n) |
| | b. Big-ch (log n) |
| | c. Omega (log n) |
| 005 | a. v (1) i.e. Constant time |
| 235. | programming is essentially recursion without repetition. |
| | a. Fast b. Dynamic page 75 |
| | U 17800000. 0808/5 |

c. Array

d. n (log n)

236. In heap sort algorithm, the total running time for heavily procedure is _.

- Big-oh(log n)
- O (1) i.e. Constant time
- Theta (log n)
- Omega (log n)
 237. Quick sort algorithm is required a lot of comparison in the _____
 condition.
- Worse case
- Best and average case
- Average case
- Best case
 - 238. In heap sort algorithm (using max heap). When every time maximum element is removed from top.
- Divide and conquer strategy helps us
- We are left with a lot
- We call merge sort algorithm
- It becomes order n2 algorithm
 239. In average-case time analysis of quick sort algorithm,
 The most balanced case for partition is where we divide the list of element into
- Three nearly equal pieces
- Single piece exactly
- Two nearly piece
- Equal no. of piece as of input element 240. Consider three matrices X,Y,Z dimensions 1×2.2×.3×4 respectively. The number of multiplication of (XYZ) is:
- 32

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| | 30 |
| • | 24 |
| • | |
| | 241. Quicksort is a/an and sorting algorithm. |
| • | In-place, not stable one |
| • | Not in-place, stable one |
| • | In-place, stable one |
| • | Not in-place, not stable one |
| 4 | 242items are not allowed in the 0/1 knapack. |
| , • j | Lighter |
| N. | Whole |
| ×V | Weighty |
| Ç. • | Fractional |
| - 1 | 243. The main purpose of mathematical analysis is measuring the |
| | required by the algorithm. |
| • | Space |
| • | Execution time and memory |
| • | Input & output |
| • | Execution time |
| | 244. Execution time of an algorithm can be measured by |
| • | Divide and conquer approach |
| • | Both brute force and divide and conquer approach |
| • | Mathematical analysis Brute force approach 245. Quick sort is based on strategy. |
| • | Brute force approach |
| | 210. (01011 2011 12 201210 11 |
| • | Graph theory |
| • | Divide-and-conquer |
| • | Dynamic programming |

- Dynamic programming
- Greedy approach

AL-JUNAID TECH INSTITUTE 246. A sorting algorithm is called as _____ if duplicate element

remain in the same relative position after sorting.

- O(n) algorithm
- Stable
- Parallel
- Complex 247. Which one sorting algorithm is best suited to sort an array of 2 million elements?
- Insert sort
- Quick sort
- Merge sort
- **Bubble** sort 248. We can use the property to devise a recursive formulation of the edit distance problem.
- Algorithm
- Small substructure
- Optimal substructure
- Real
 - 249. While sorting. The ordered domain means for any two input elements x and y satisfies only.
- All of the above
- x > y
- x < y
- $\mathbf{x} = \mathbf{y}$

8n2 + 2n - 3 will eventually exceed c2*(n) no matter how large we make .

- 2n
- this equation

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| • | c2 | |
| | 251 is a method of solving a problem in which we check | |
| | all possible solution to the problem to find the solution we need. | |
| • | Sorting algorithm | |
| • | Greedy approach | |
| • | Plane-sweep algorithm | |
| • | Brute-force algorithm | |
| | 252. In quick sort algorithm, provost form | |
| • | Graph | |
| • | Stack | |
| • | Binary search tree | |
| y | Queue | |
| 7. | 253. In asymptotical analysis of $n(n-3)$ and $4n*n$, as n becomes large, | |
| | the dominant (fastest growing) term is some constant time | |
| • | n+1 | |
| • | <mark>n*n</mark> | |
| • | n | |
| • | n-1 | |
| | 254. If Matrix-A has dimensions "3×2" and Matrix-B has dimensions | |
| | "2×3", then multiplication of Matrix –A and Matrix-B will result a | |
| | new Matrix-C having dimensions | |
| • | 2×3 | |
| • | 2×2 | |
| • | 2×2 3×2 3×3 255 Replace approximation is a separation on an idealized RAM. | |
| • | 3×3 | |
| | 255. Boolean operation is a operation on an idealized KAIVI | |
| _ | model of computation. | |
| • | Advance | |
| • | Normal | |

- Basic
- Starting
 256. There are entries in the Edit Distance Matrix.
- \bullet $\Theta(n^2)$
- O (n+100)
- O (n)
- O (n+2)
 - 257. Counting sort is suitable for sorting the elements within range 1 to P. where

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- P is undetermined
- P is small
- P is very large
- P is large
 - 258. Suppose we have 4 matrices A,B,C,D. what is correct expansion of m[1,2] in chain matrix multiplication?
- m[1,2] = m[1,1] + m[2,2] + p0 . p1. p3
- $m[1,2] = m[1,1] + m[2,2] + p0 \cdot p1 \cdot p3$
- m[1,2] = m[1,1] + m[2,2] + p0 . p1. p3
- m[1,2] = m[1,1] + m[2,2] +p0 . p1. p3
 259. Which one is not passed as parameter in Quick Sort algorithm?
- Array (containing input elements)
- Middle of the array
- Start of the array
- End of the array
 260. In asymptotical analysis of n*(5+2)-3. As n becomes large, the dominant (fastest growing) term is some constant times
- n+1
- n*n
- n

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| • n_1 261 For values of a pay algorithm is foot arough |
| 261. For values of n, any algorithm is fast enough. |
| • Medium |
| • Small |
| • Infinity |
| • Large |
| 262. Dynamic programming algorithms often use some kind of |
| to store the result of intermediate sub-problems. |
| • Stack |
| • Loop |
| • Table |
| Variable |
| 263. In selection problem, the Sieve technique works in |
| One complete go |
| • Constant time |
| Non-recursive manner |
| • Phases |
| 264. In heap Sort algorithm, the maximum levels an element can mov |
| upward is |
| • Theta (log n) |
| • O (1) i.e. Constant time |
| • Omega (log n) |
| • Big-oh (log n) |
| 265. While analysis of the brute-force maxima algorithm, an array |
| storted in the reverse order is the type of case input. |
| • Worst |
| • Best |
| • Somewhat |

- Average

What type of instructions Random Access Machine (RAM) can execute?

- ► Algebraic and logic
- ► Geometric and arithmetic

► Arithmetic and logic (Page 10)

- ► Parallel and recursive
- For Chain Matrix Multiplication we can not use divide and conquer approach because, 267.

► We do not know the optimum k (Page 86)

- ► We use divide and conquer for sorting only
- ► We can easily perform it in linear time
- ► Size of data is not given

268. What is the total time to heapify?

- ➤ O(log n) (Page 43)
- O(n log n)
- ► O(n2 log n)
- ➤ O(log2 n)

is a graphical representation of an algorithm 269.

- notation
 - notation
 - ➤ Flowchart
 - ► Asymptotic notation
- A RAM is an idealized machine with 270. random-access memory.
 - ▶ 256MB
 - ► 512MB
 - ➤ an infinitely large (Page 10)
 - ▶ 100GB
- 271. What type of instructions Random Access Machine (RAM) can execute? Choose best answer
- ► Algebraic and logic
- ► Geometric and arithmetic

► Arithmetic and logic

- ► Parallel and recursive
- What is the solution to the recurrence T(n) = T(n/2)+n.
 gn)
 (Page 37) 272.
- ► O(logn)

► O(n) (Page 37)

- ► O(nlogn)
- ► O(n 2)