

# A Dual Framework for Low-rank Tensor Completion

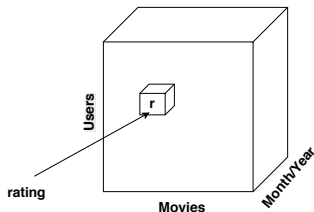
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## 1 Preliminaries

## 2 A Dual Framework for Tensor Completion

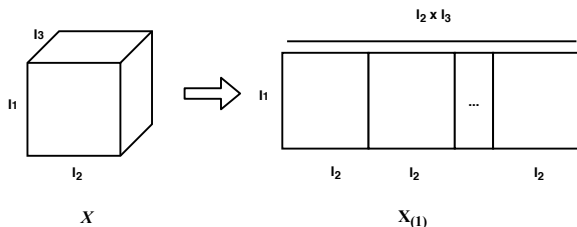
- Introduction
- Proposed Variant of Trace Norm
- Dual Formulation
- Optimization
- Experimental Results
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- A **Tensor** is a multi-way extension of a matrix.



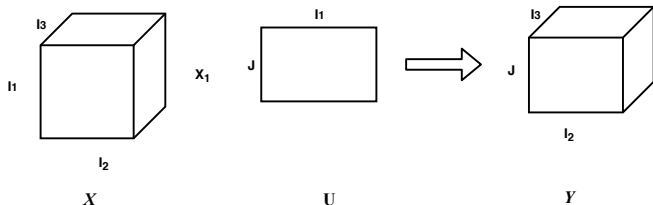
- Tensors are used for representing multidimensional data.

- **Tensor Matricization or Tensor Unfolding** is the process of reordering the elements of an  $N$ -order tensor into a matrix. The mode- $n$  unfolding of  $\mathcal{X}$ , denoted by  $\mathbf{X}_{(n)}$ , arranges the mode- $n$  fibers to be the columns of resulting matrix.



- **Tensor-Matrix Multiplication** The  $n$ -mode (matrix) product of a tensor  $\mathcal{X} \in \mathbb{R}^{I_1 \times I_2 \times \dots \times I_N}$  with a matrix  $\mathbf{U} \in \mathbb{R}^{J \times I_n}$  is denoted by  $\mathcal{X} \times_n \mathbf{U}$  and is of size  $I_1 \times \dots \times I_{n-1} \times J \times I_{n+1} \times \dots \times I_N$ .

$$\mathcal{Y} = \mathcal{X} \times_n \mathbf{U} \iff \mathbf{Y}_{(n)} = \mathbf{U} \mathbf{X}_{(n)}$$



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# Introduction

- Tensors can be used to model multi-dimensional data.
- In practice, often the multidimensional datasets are incomplete.

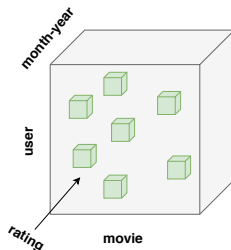


Figure : Partially observed tensor, green represents observed entries.

- **Tensor Completion:** The problem of imputing or predicting missing values in a partially observed tensor.
- Applications:
  - Image Completion
  - Recommendation Systems
  - Video Completion
  - Link prediction in Knowledge Graphs, Social Networks etc
  - ...



- A common modeling assumption for tensor completion: the tensor is low-rank.
- Common approaches:
  - Factorization based
  - Trace-norm regularization based

**Trace Norm** based Formulation:

$$\min_{\mathbf{W} \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_K}} \|\mathbf{W}_\Omega - \mathcal{Y}_\Omega\|_F^2 + \frac{1}{\lambda} \|\mathbf{W}\|_*$$

where  $\mathcal{Y}$  is a partially observed tensor,  $\Omega$  is the sparsity pattern,  $\|\cdot\|_*$  is the trace norm and  $\lambda > 0$  is the regularization constant.

A rank- $(r_1, r_2, \dots, r_K)$  tensor  $\mathcal{X} \in \mathbb{R}^{n_1 \times n_2 \times \dots \times n_K}$  can be written as:

$$\mathcal{X} = \mathcal{G} \times_1 \mathbf{U}_1 \times_2 \mathbf{U}_2 \dots \times_K \mathbf{U}_K,$$

where

- $\mathbf{U}_k \in \mathbb{R}^{n_k \times r_k}$  are left singular values from SVD of  $\mathcal{X}_{(k)}$ .
- $\mathcal{G} \in \mathbb{R}^{r_1 \times r_2 \times \dots \times r_K}$  is the core tensor.

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- The above decomposition is called **Tucker decomposition**.

- $\mathcal{G}$  is not diagonal in general.
- Not straightforward to generalize trace norm to tensors.

# Trace Norm of Tensor

Strategies for tensor trace norm [Tomioka et al., 2010].

- 1 Tensor as a Matrix:

$$\|\mathcal{W}\|_* := \|\mathbf{W}_{(k)}\|_*, \text{ for some } 1 \leq k \leq K$$

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- 3 Latent Trace Norm:

$$\|\mathcal{W}\|_* := \sum_{k=1}^K \inf_{\mathbf{W}^{(k)} \in \mathbb{R}^{n_1 \times \dots \times n_K}} \|\mathbf{W}^{(k)}\|_*$$



- ✓ Latent Trace Norm is showed to produce better results [Tomioka and Suzuki, 2013].
- ✗ But, Latent Trace Norm learns a skewed-mixture in sparse settings.

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# Non-Sparse Trace Norm

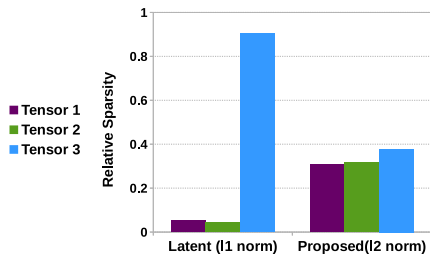
We propose the following variant of trace norm:

$$\min_{\mathbf{w}^{(k)} \in \mathbb{R}^{n_1 \times \dots \times n_K}} \left\| \sum_k \mathbf{w}_\Omega^{(k)} - \mathbf{y}_\Omega \right\|_F^2 + \sum_k \frac{1}{\lambda_k} \|\mathbf{w}_{(k)}^{(k)}\|_*^2, \quad (1)$$

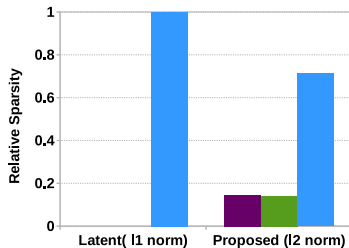
where  $\mathbf{W} = \sum_k \mathbf{w}^{(k)}$  is the learned tensor.

# Non-Sparse Trace Norm (cont.)

$$\text{Relative sparsity} = \frac{\|\mathcal{W}^{(k)}\|_F}{\sum_k \|\mathcal{W}^{(k)}\|_F}$$



(a) Ribeira



(b) Baboon

Figure : (a) & (b) Relative sparsity of each tensor in the mixture of tensors for Ribeira and Baboon datasets. Our proposed formulation learns a  $\ell_2$ -norm based non-sparse combination of tensors

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## Theorem

An equivalent minimax formulation of the problem (1) is

$$\min_{\Theta_1 \in \mathcal{P}^{n_1}, \dots, \Theta_K \in \mathcal{P}^{n_K}} \max_{\mathcal{Z} \in \mathcal{C}} \langle \mathcal{Z}, \mathcal{Y}_\Omega \rangle - \frac{1}{4} \|\mathcal{Z}\|_F^2 - \sum_k \frac{\lambda_k}{2} \langle \Theta_k, \mathcal{Z}_{(k)} \mathcal{Z}_{(k)}^\top \rangle, \quad (2)$$

where  $\mathcal{Z}$  is the dual tensor variable corresponding to the primal problem (1) and  $\mathcal{Z}_{(k)}$  is the mode- $k$  unfolding of  $\mathcal{Z}$ . The set  $\mathcal{C} := \{\mathcal{Z} \in \mathbb{R}^{n_1 \times \dots \times n_K} : \mathcal{Z}_{(i_1, \dots, i_K)} = 0, (i_1, \dots, i_K) \notin \Omega\}$  constrains  $\mathcal{Z}$  to be a sparse tensor with  $|\Omega|$  non-zero entries. Let  $\{\Theta_1^*, \dots, \Theta_K^*, \mathcal{Z}^*\}$  be the optimal solution of (2). The optimal solution of (1) is given by  $\mathcal{W}^* = \sum_k \mathcal{W}^{(k)*}$ , where  $\mathcal{W}^{(k)*} = \lambda_k (\mathcal{Z}^* \times_k \Theta_k^*) \forall k$  and  $\times_k$  denotes the tensor-matrix multiplication along mode  $k$ .

# Dual Formulation (cont.)

## Corollary

(Representer theorem) The optimal solution of the primal problem (1) admits a representation of the form:  $\mathcal{W}^{(k)*} = \lambda_k(\mathcal{Z} \times_k \Theta_k) \forall k$ , where  $\mathcal{Z} \in \mathcal{C}$  and  $\Theta_k$  are PSD with  $\text{trace}(\Theta_k) = 1$ .

The diagram shows a 3D cube on the left labeled  $\mathcal{W}^{(k)*}$ . To its right is an equals sign. To the right of the equals sign is another 3D cube labeled  $\mathcal{Z}$ . To the right of the  $\mathcal{Z}$  cube is the symbol  $\times_k$ . To the right of  $\times_k$  is a 2D square labeled  $\Theta_k$ .

- **Fixed-rank parameterization of  $\Theta_k$ .** We propose to explicitly constrain the rank of  $\Theta_k$  to  $r_k$  by  $\Theta_k = \mathbf{U}_k \mathbf{U}_k^\top$ , where  $\mathbf{U}_k \in \mathcal{S}_{r_k}^{n_k}$  and  $\mathcal{S}_r^n := \{\mathbf{U} \in \mathbb{R}^{n \times r} : \|\mathbf{U}\|_F = 1\}$ .



- **Fixed-rank dual formulation**

$$\text{Problem } \mathcal{D} : \min_{u \in \mathcal{S}_{r_1}^{n_1} \times \dots \times \mathcal{S}_{r_K}^{n_K}} g(u),$$

where  $u = (\mathbf{U}_1, \dots, \mathbf{U}_K)$  and  $g : \mathcal{S}_{r_1}^{n_1} \times \dots \times \mathcal{S}_{r_K}^{n_K} \rightarrow \mathbb{R}$  is the function

$$g(u) := \max_{\mathcal{Z} \in \mathcal{C}} \langle \mathcal{Z}, \mathcal{Y}_\Omega \rangle - \frac{1}{4} \|\mathcal{Z}\|_F^2 - \sum_k \frac{\lambda_k}{2} \left\| \mathbf{u}_k^\top \mathcal{Z}^{(k)} \right\|_F^2.$$

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# Riemannian Optimization Algorithm

- $S_r^n$  is the *spectrahedron* manifold [Journée et al., 2010].
- Optimization on spectrahedron manifold is handled in the Riemannian optimization framework.
- We propose Riemannian TR algorithms (**TR-MM**) for  $\mathcal{D}$ .

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Dataset	Dimensions	Task
Ribeira	$203 \times 268 \times 33$	Hyperspectral Image Completion
Tomato	$242 \times 320 \times 167$	Video Completion
Baboon	$256 \times 256 \times 3$	Image Completion
MovieLens10M	$71567 \times 10681 \times 731$	Recommendation
FB15k-237	$14541 \times 14541 \times 237$	Link Prediction
YouTube (subset)	$1509 \times 1509 \times 5$	Link Prediction
YouTube (full)	$15088 \times 15088 \times 5$	Link Prediction

Table : Datasets for Tensor Completion

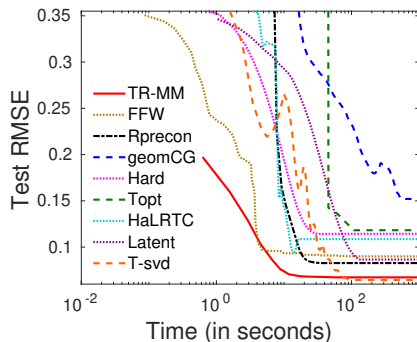
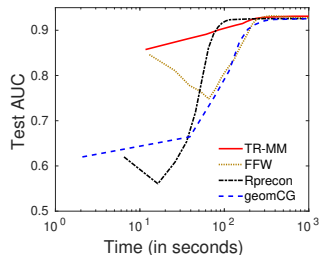
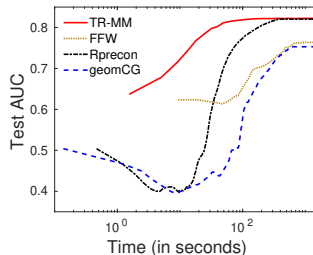


Figure : Evolution of test RMSE on Ribeira (Image Completion Dataset)

# Results (cont.)



(a) YouTube (full)



(b) FB15K-237

Figure : Evolution of test AUC on link prediction datasets YouTube and FB15K-237.

# Results (cont.)

	TR-MM	FFW	Rprecon	geomCG	Hard	Topt	HaLRTC	Latent	T-svd	BayesCP
<u>RMSE reported</u>										
Ribeira	0.067	0.088	0.083	0.156	0.114	0.127	0.095	0.087	<b>0.064</b>	0.154
Tomato	<b>0.041</b>	0.045	0.052	0.052	0.060	0.102	0.202	0.046	0.042	0.103
Baboon	<b>0.121</b>	0.133	0.128	0.128	0.126	0.130	0.247	0.459	0.146	0.159
ML10M	0.840	0.895	<b>0.831</b>	0.844	—	—	—	—	—	—
<u>AUC reported</u>										
YouTube (subset)	<b>0.957</b>	0.954	0.941	0.941	0.954	0.941	0.783	0.945	0.941	0.950
YouTube (full)	<b>0.932</b>	0.929	0.926	0.926	—	—	—	—	—	—
FB15k-237	<b>0.823</b>	0.764	0.821	0.785	—	—	—	—	—	—

**Table :** Generalization performance across several applications: hyperspectral-image/video/image completion, movie recommendation, and link prediction.



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# Conclusion

- We propose a variant of Latent trace norm that learns a non-skewed mixture of tensors.
- We propose a dual framework for analyzing the formulation.
- The dual framework achieves better generalization performance.

## Conclusion (cont.)



- Madhav Nimishakavi, Pratik Jawanpuria and Bamdev Mishra. A Dual Framework for Low-rank Tensor Completion. In *In Advances of Neural Information Processing Systems (NIPS)*, 2018.

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